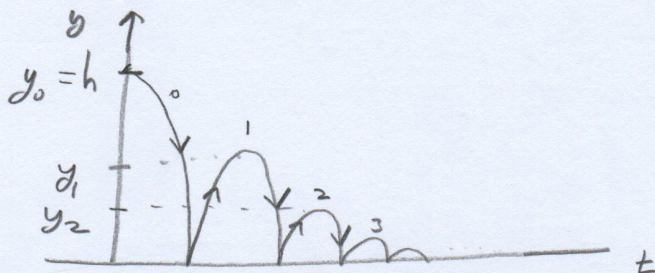


5.1
Exercise

Inelastic collision of a ball with floor

①



$$\eta^2 = \frac{K_{final}}{K_{initial}}$$

$$K_{initial} = \frac{1}{2} m v_0^2 = mgh$$

$$v_0^2 = 2gh$$

$$v_0 = \sqrt{2gh}$$

$$K_{final} = \eta^2 K_{initial}$$

$$= \eta^2 mgh$$

$$= \eta^2 mgy_0$$

$$= mgy_1$$

$$\text{Thus, } y_1 = \eta^2 y_0 = \eta^2 h$$

$$y_2 = \eta^2 y_1 = \eta^4 h$$

$$y_3 = \eta^6 h$$

$$\dots y_N = \eta^N h$$

$$T_{\text{time}} = T_0 + T_1 + T_2 + \dots$$

$$\text{0: } h = \frac{1}{2} g T_0^2 \rightarrow T_0 = \sqrt{\frac{2h}{g}}$$

~~Time~~

$$\text{1: } \eta^2 h = \frac{1}{2} g t^2 \rightarrow T_1 = 2 \cdot \eta t = 2 \eta \sqrt{\frac{2h}{g}}$$

(2)

 $T_{4.1},$

$$T = \sqrt{\frac{2h}{g}} (1 + 2\eta + 2\eta^2 + \dots)$$

$$= \sqrt{\frac{2h}{g}} [(1 + \eta + \eta^2 + \eta^3 + \dots) + (\eta + \eta^2 + \eta^3 + \dots)]$$

$$= \sqrt{\frac{2h}{g}} \left[\left(\frac{1}{1-\eta} \right) + \left(\frac{\eta}{1-\eta} \right) \right]$$

$$= \sqrt{\frac{2h}{g}} \left(\frac{1+\eta}{1-\eta} \right)$$

$$1 + \eta + \eta^2 + \dots = \left(\frac{1}{1-\eta} \right)$$

$$\eta + \eta^2 + \dots = \left(\frac{1}{1-\eta} \right) - 1$$

$$= \frac{1 - (1-\eta)}{1-\eta}$$

~~WAA~~

$$= \frac{\eta}{1-\eta}$$

Limiting cases:

$$\underline{\eta = 0:}$$

$$T = \sqrt{\frac{2h}{g}}$$

(time to fall from $y=h$ to $y=0$)

$$\underline{\eta = 1:}$$

$$T = \infty \quad (\text{ball bounces forever})$$

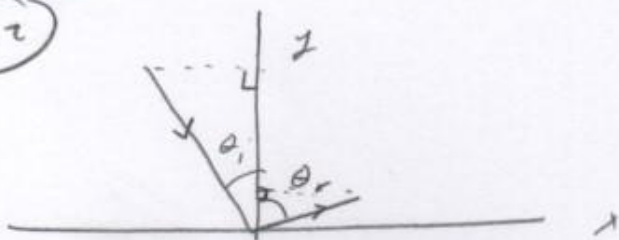
$$2 \left(\frac{1}{1-\eta} \right) - 1 = \frac{1}{1-\eta} (2 - (1-\eta))$$

$$= \frac{1+\eta}{1-\eta}$$

~~Post~~
Exercise

5.2

Angle of incidence vs. angle of reflection for inelastic collisions



$$p_{x, \text{final}} = p_{x, \text{init}}$$

$$p_{y, \text{final}} = \eta p_{y, \text{init}}$$

(For any η involves the square of the velocity)

✓ Thus, $v_{x, \text{final}} = v_{x, \text{init}} \equiv v_x$

$$v_{y, \text{final}} = \sqrt{\eta} v_{y, \text{init}}$$

✓ $v_{\text{final}}^2 = v_x^2 + v_y^2$

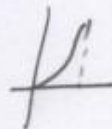
$$v_f^2 = v_{xf}^2 + v_{yf}^2 = v_x^2 + v_{yf}^2 = v_x^2 + \eta^2 v_{yi}^2$$

✓ $v_i^2 = v_{xi}^2 + v_{yi}^2 = v_x^2 + v_{yi}^2$

$$\tan \theta_i = \frac{v_{xi}}{v_{yi}} = \frac{v_x}{v_{yi}}$$

$$\tan \theta_r = \frac{v_{xf}}{v_{yf}} = \frac{v_x}{\sqrt{\eta} v_{yi}} = \frac{1}{\sqrt{\eta}} \tan \theta_i$$

Thus, $\boxed{\tan \theta_r = \frac{1}{\sqrt{\eta}} \tan \theta_i}$



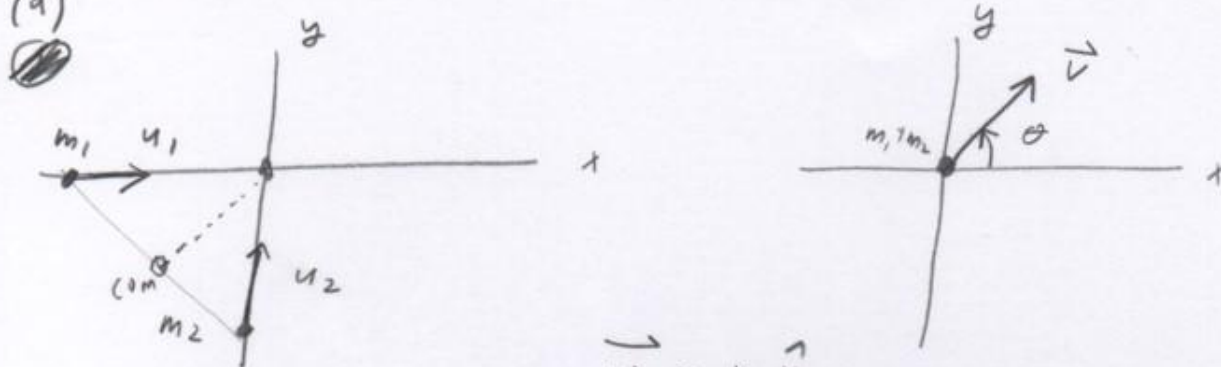
$\eta = 1$: $\tan \theta_r = \tan \theta_i \rightarrow \theta_r = \theta_i$

$\eta = 0$: $\tan \theta_r = \infty \tan \theta_i \rightarrow \theta_r = \frac{\pi}{2}$



Exercise 5.3 Perfectly inelastic collision in different ref frames ①

(a)



(before)

$$\vec{u}_1 = u_1 \hat{x}$$

$$\vec{u}_2 = u_2 \hat{y}$$

$$\vec{p}_i = \vec{p}_f$$

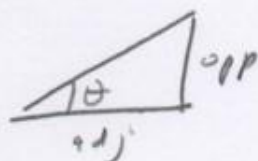
conservation of momentum

$$m_1 u_1 \hat{x} + m_2 u_2 \hat{y} = (m_1 + m_2) \vec{V} \equiv M \vec{V}$$

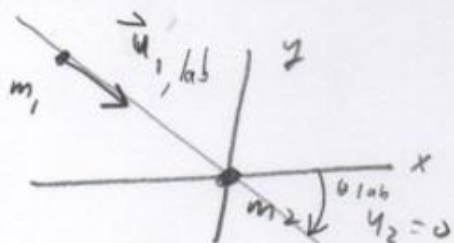
$$\text{Thus, } \vec{V} = \left(\frac{m_1 u_1}{M} \right) \hat{x} + \left(\frac{m_2 u_2}{M} \right) \hat{y}$$

$$\text{speed: } V = \frac{\sqrt{m_1^2 u_1^2 + m_2^2 u_2^2}}{M}$$

$$\tan \theta = \frac{\left(\frac{m_2 u_2}{M} \right)}{\left(\frac{m_1 u_1}{M} \right)} = \frac{m_2 u_2}{m_1 u_1}$$



(b) Lab frame / m_2 at rest; subtract $u_2 \hat{y}$ from all velocities



(before)

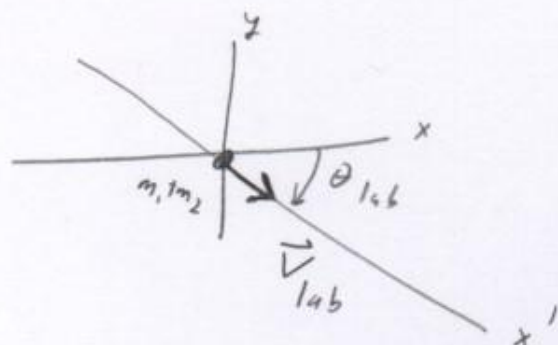
$$\vec{u}_{1,lab} = u_1 \hat{x} - u_2 \hat{y}, \quad \vec{u}_{2,lab} = \vec{0}$$

$$\vec{p}_{lab,i} = m_1 \vec{u}_{1,lab}$$

$$\vec{p}_{lab,f} = (m_1 + m_2) \vec{V}_{lab}$$

$$\text{Thus, } \vec{V}_{lab} = \left(\frac{m_1}{M} \right) \vec{u}_{1,lab} = \left(\frac{m_1}{M} \right) [u_1 \hat{x} - u_2 \hat{y}]$$

After:



speed: $V_{lab} = \frac{m_1}{m} \sqrt{u_1^2 + u_2^2}$

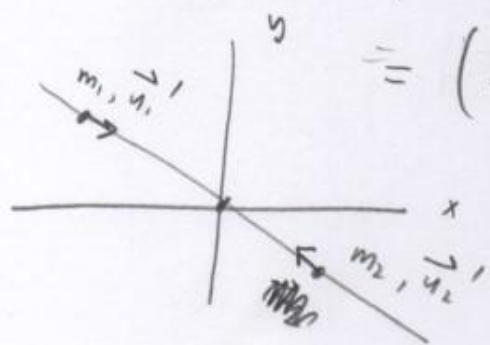
direction: $\tan \theta_{lab} = -\frac{u_2}{u_1} \quad (< 0)$

(c) Barycenter frame (com at origin)

→ combined mass at rest at origin after collision

Then, ~~add~~ subtract $\vec{V}_{lab}$ from $\vec{u}_{1,lab}$, $\vec{u}_{2,lab}$ to go to barycenter frame

$$\begin{aligned} \vec{u}_1' &= \vec{u}_{1,lab} - \vec{V}_{lab} \\ &= (u_1 \hat{x} - u_2 \hat{y}) - \left(\frac{m_1}{m}\right) [u_1 \hat{x} - u_2 \hat{y}] \\ &= \left(1 - \frac{m_1}{m}\right) (u_1 \hat{x} - u_2 \hat{y}) \\ &= \frac{m_2}{m} (u_1 \hat{x} - u_2 \hat{y}) \end{aligned}$$

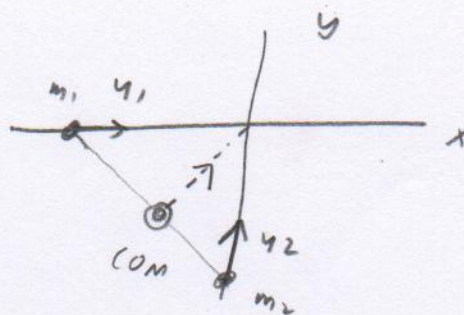


$$\vec{u}_2' = \vec{u}_{2,lab} - \vec{V}_{lab} = -\frac{m_1}{m} (u_1 \hat{x} - u_2 \hat{y})$$

Original frame:

$$\vec{u}_1 = u_1 \hat{x}$$

$$\vec{u}_2 = u_2 \hat{y}$$



Calculate $\vec{u}_1 - \vec{V}$, $\vec{u}_2 - \vec{V}$:

$$\vec{u}_1 - \vec{V} = u_1 \hat{x} - \left(\left(\frac{m_1 u_1}{M} \right) \hat{x} + \left(\frac{m_2 u_2}{M} \right) \hat{y} \right)$$

$$= \left(1 - \frac{m_1}{M} \right) u_1 \hat{x} - \frac{m_2 u_2}{M} \hat{y}$$

$$= \frac{m_2}{M} (u_1 \hat{x} - u_2 \hat{y})$$

$$= \vec{u}_1'$$

$$\vec{u}_2 - \vec{V} = u_2 \hat{y} - \left(\left(\frac{m_1 u_1}{M} \right) \hat{x} + \left(\frac{m_2 u_2}{M} \right) \hat{y} \right)$$

$$= - \frac{m_1 u_1}{M} \hat{x} + \left(1 - \frac{m_2}{M} \right) u_2 \hat{y}$$

$$= - \frac{m_1}{M} (u_1 \hat{x} - u_2 \hat{y})$$

$$= \vec{u}_2'$$

Thus, $\boxed{\vec{u}_1 - \vec{V} = \vec{u}_1', \quad \vec{u}_2 - \vec{V} = \vec{u}_2'}$

(So barycentre frame is moving with velocity $\vec{V}$ w.r.t original frame)

Relating lab and barycenter frames

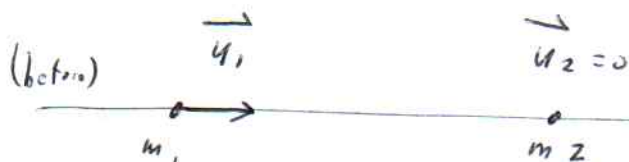
EXAMPLE

5.1

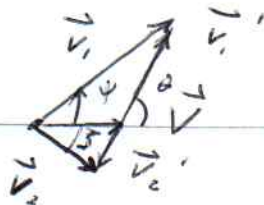
Exercise

5.4

Lab

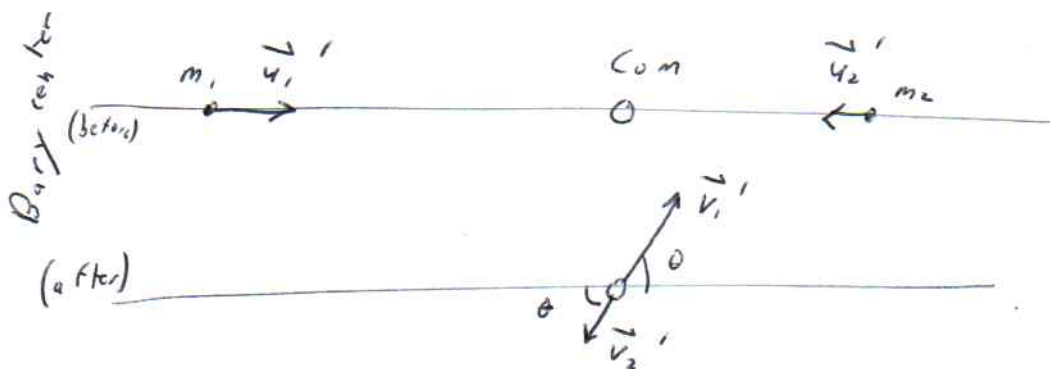


(after)

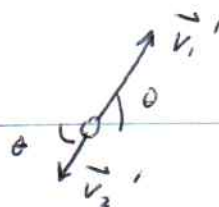


$$\begin{aligned}\vec{V}_1' &= \vec{V} + \vec{V}_1' \\ \vec{V}_2' &= \vec{V} + \vec{V}_2'\end{aligned}$$

primes denote w.r.t barycenter frame



(after)



Barycenter Frame

$$COM = 0 \rightarrow m_1 \vec{u}_1' + m_2 \vec{u}_2' = 0$$

$$m_1 u_1' = m_2 u_2' \quad \text{where} \quad \begin{aligned} u_1' &= |\vec{u}_1'| \\ u_2' &= |\vec{u}_2'| \end{aligned}$$

$$\text{Also: } m_1 v_1' = m_2 v_2'$$

Energy:

$$\frac{1}{2} m_1 u_1'^2 + \frac{1}{2} m_2 u_2'^2 = \frac{1}{2} m_1 v_1'^2 + \frac{1}{2} m_2 v_2'^2$$

$$\cancel{\frac{1}{2}} m_1 (u_1'^2 - v_1'^2) = \cancel{\frac{1}{2}} m_2 (v_2'^2 - u_2'^2)$$

$$m_1 (u_1' - v_1')(u_1' + v_1') = m_2 (v_2' - u_2')(v_2' + u_2')$$

$$(u_1' - v_1')(m_1 u_1' + m_1 v_1') = (v_2' - u_2')(m_2 v_2' + m_2 u_2')$$

$$\underbrace{\quad}_{2m_1 u_1'} \quad \underbrace{\quad}_{m_1 v_1' + m_1 u_1'}$$

$$\text{so } u_1' - v_1' = v_2' - u_2'$$

$$u_1' - v_1' = v_2' - u_2'$$

$$u_1' - v_1' = \frac{m_1}{m_2} v_1' - \frac{m_1}{m_2} u_1'$$

$$\left(1 + \frac{m_1}{m_2}\right) u_1' = \left(1 + \frac{m_1}{m_2}\right) v_1'$$

$$\rightarrow \boxed{u_1' = v_1'}$$

Similarly: $\boxed{u_2' = v_2'}$

com velocity $\vec{V}$:

$$(m_1 + m_2) \vec{V} = m_1 \vec{u}_1 + m_2 \vec{u}_2$$

$$\vec{V} = \frac{m_1}{M} \vec{u}_1, \text{ where } M = m_1 + m_2$$

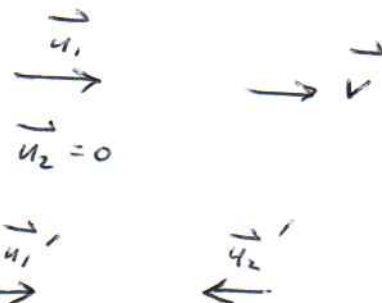
Body centre quantities:

$$\vec{u}_1' = \vec{u}_1 - \vec{V}$$

$$\vec{u}_2' = \vec{u}_2 - \vec{V} = -\vec{V}$$

$$\vec{v}_1' = \vec{v}_1 - \vec{V}$$

$$\vec{v}_2' = \vec{v}_2 - \vec{V}$$



In terms of magnitudes:

$$u_1' = u_1 - V = u_1 - \frac{m_1}{M} u_1 = u_1 \left(1 - \frac{m_1}{M}\right) = u_1 \frac{m_2}{M} = (v_1')$$

$$u_2' = +V = \frac{m_1}{M} u_1 (= v_2')$$

Components of $\vec{v}_1, \vec{v}_2$ in lab frame:

$$v_{1x} = v_1 \cos \psi = v_{1x}' + V = v_1' \cos \theta + \frac{m_1}{M} u_1$$

$$= u_1 \frac{m_2 \cos \theta}{M} + \frac{m_1}{M} u_1$$

$$= \frac{u_1}{M} (m_2 \cos \theta + m_1)$$

$$V_{1y} = V_1 \sin \psi = V_{1y}' = V_1' \sin \theta = u_1 \frac{m_2 \sin \theta}{M}$$

$$\text{Also, } V_1 = \sqrt{V_{1x}^2 + V_{1y}^2}$$

$$= \frac{u_1}{M} \sqrt{(m_2 \cos \theta + m_1)^2 + \cancel{m_2^2} (m_2 \sin \theta)^2}$$

$$= \frac{u_1}{M} \sqrt{\underbrace{m_2^2 \cos^2 \theta + m_1^2 + 2m_1 m_2 \cos \theta + m_2^2 \sin^2 \theta}_{= m_2^2}}$$

$$= \frac{u_1}{M} \sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}$$

$$\text{So } \cos \psi = \frac{\cancel{u_1} V_{1x}}{\cancel{u_1} V_1} = \frac{V_{1x}}{V_1}$$

$$= \frac{\cancel{u_1} (m_2 \cos \theta + m_1)}{\cancel{u_1} \sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}}$$

$$= \frac{m_2 \cos \theta + m_1}{\sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}}$$

Repeat for target particle:

$$\cos \theta \cos \pi - \sin \theta \sin \pi$$

$$V_{2x} = V_2 \cos \phi = V_{2x}' + V$$

$$= V_2' \cos(\theta + \pi) + \frac{m_1 u_1}{M}$$

$$= -V_2' \cos \theta + \frac{m_1 u_1}{M}$$

$$= -\frac{m_1 u_1}{M} \cos \theta + \frac{m_1 u_1}{M}$$

$$= \frac{m_1 u_1}{M} (1 - \cos \theta)$$

$$\begin{aligned}
 V_{2y} &= V_2 \sin \zeta = V_{2y}' \quad \text{Mistake} \\
 &= V_2' \sin(\theta + \pi) \quad \text{Mistake} \\
 &= -u_1 \frac{m_1}{M} \sin \theta
 \end{aligned}$$

$$\begin{aligned}
 \sin(\theta + \pi) &= \sin \theta \cos \pi + \cos \theta \sin \pi \\
 &= -\sin \theta
 \end{aligned}$$

$$\begin{aligned}
 \text{Thus, } V_2 &= \sqrt{V_{2x}^2 + V_{2y}^2} \\
 &= \frac{u_1 m_1}{M} \sqrt{(1 - \cos \theta)^2 + \sin^2 \theta} \\
 &= \frac{u_1 m_1}{M} \sqrt{1 + \cos^2 \theta + \sin^2 \theta - 2 \cos \theta} \\
 &= \frac{u_1 m_1}{M} \sqrt{2(1 - \cos \theta)}
 \end{aligned}$$

$$\begin{aligned}
 \rightarrow \cos \zeta &= \frac{V_{2x}}{V_2} \\
 &= \frac{\frac{m_1 u_1}{M} (1 - \cos \theta)}{\frac{u_1 m_1}{M} \sqrt{2(1 - \cos \theta)}} \\
 &= \sqrt{\frac{1 - \cos \theta}{2}}
 \end{aligned}$$

$$p_1 = \frac{m_1 u_1}{M} = \frac{m_1}{m_2} \frac{u_1 m_2}{M}$$

$$p_2 = \frac{m_1 u_1}{M} = \frac{m_1 u_1}{m_2 M}$$

$$\begin{aligned}
 \cos(2\pi - \zeta) &= \cos 2\pi \cos \zeta + \sin 2\pi \sin \zeta \\
 &= \cos \zeta
 \end{aligned}$$

Thus, for elastic scattering

$$\cos \psi = \frac{m_2 \cos \theta + m_1}{\sqrt{m_1^2 + m_2^2 + 2 m_1 m_2 \cos \theta}}$$

$$\cos \zeta = \sqrt{\frac{1 - \cos \theta}{2}} = \sin\left(\frac{\theta}{2}\right)$$

$$\begin{aligned}
 \cos 2\theta &= \cos^2 \theta - \sin^2 \theta \\
 &= 1 - 2 \sin^2 \theta
 \end{aligned}$$

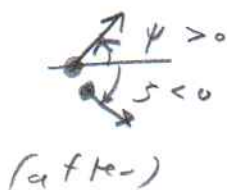
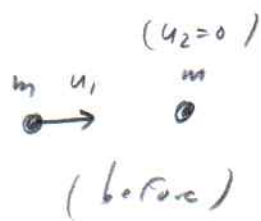
$$\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$$

$$\sin \theta = \sqrt{\frac{1 - \cos 2\theta}{2}}$$

$$\cos \zeta = \sin\left(\frac{\theta}{2}\right)$$

$$\cos\left(\frac{\pi}{2} - \frac{\theta}{2}\right) = \cos \frac{\pi}{2} \cos \frac{\theta}{2} + \sin \frac{\pi}{2} \sin \frac{\theta}{2}$$

Exercise 5.5 Show that for equal-mass elastic scattering, $|\psi| + |\delta| = \pi/2$



Elastic scattering:

$$\cos \psi = \frac{m_2 \cos \theta + m_1}{\sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}}$$

θ : angle in
barycenter
frame

$$\cos \delta = \sin \left(\frac{\theta}{2} \right)$$

$m_1 = m_2 \equiv m$ (Equal mass)

$$\cos \psi = \frac{\cos \theta + 1}{\sqrt{2 + 2 \cos \theta}} = \sqrt{\frac{\cos \theta + 1}{2}} = \cos \left(\frac{\theta}{2} \right)$$

Thus, $\boxed{\psi = \frac{\theta}{2}}$

$$\begin{aligned} \sin x &= \cos \left(x - \frac{\pi}{2} \right) \\ &= \underbrace{\cos x \cos \frac{\pi}{2}}_{=0} + \underbrace{\sin x \sin \frac{\pi}{2}}_{=1} \end{aligned}$$

So $\cos \delta = \sin \left(\frac{\theta}{2} \right) = \cos \left(\frac{\theta}{2} - \frac{\pi}{2} \right)$

$\rightarrow \boxed{\delta = \frac{\theta}{2} - \frac{\pi}{2}} < 0$

Hence, $\boxed{\psi - \delta = \frac{\theta}{2} - \left(\frac{\theta}{2} - \frac{\pi}{2} \right) = \frac{\pi}{2}}$

$$\begin{aligned} |\delta| &= \left| \frac{\theta}{2} - \frac{\pi}{2} \right| \\ &= \frac{\pi}{2} - \frac{\theta}{2} \end{aligned}$$

$$\begin{aligned} |\psi| + |\delta| &= \frac{\theta}{2} + \frac{\pi}{2} - \frac{\theta}{2} \\ &= \frac{\pi}{2} \end{aligned}$$

$$\begin{aligned} \cos 2x &= \cos^2 x - \sin^2 x \\ &= 2 \cos^2 x - 1 \end{aligned}$$

$$\cos^2 x = \frac{1 + \cos 2x}{2}$$

Newtonian Scattering

$y_{min} = 1$

Section 5.5

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(1)

$$\phi_{min} = \int_0^1 \frac{du}{\sqrt{\frac{2\mu R^2}{l^2} \left(\epsilon - \frac{l^2}{2\mu r^2} + \frac{GM_\mu}{r} \right)}}$$

$$= \int_0^1 \frac{du}{\sqrt{\frac{2\mu R^2}{l^2} \epsilon - u^2 + \frac{2GM_\mu^2 R}{l^2} u}}$$

$$= \int_0^1 \frac{du}{\sqrt{\frac{2\mu R^2}{l^2} \epsilon + \frac{2GM_\mu^2 R}{l^2} u - u^2}}$$

$$= \int_0^1 \frac{du}{\sqrt{a + bu + cu^2}}$$

$$a = \frac{2\mu R^2 \epsilon}{l^2}, \quad b = \frac{2GM_\mu^2 R}{l^2}, \quad c = -1$$

$$\int_0^1 \frac{du}{\sqrt{R}} = -\frac{1}{\sqrt{-c}} \arcsin \left(\frac{2cu+b}{\sqrt{-\Delta}} \right) \Big|_0^1$$

$$= -\frac{1}{\sqrt{-c}} \left[\arcsin \left(\frac{2c+b}{\sqrt{-\Delta}} \right) - \arcsin \left(\frac{b}{\sqrt{-\Delta}} \right) \right]$$

$$b = \frac{2R}{\alpha}$$

where

$$\alpha = \frac{l^2}{GM_\mu^2}$$

(later, rectify for ellipse)

$$-\Delta = b^2 - 4ac = \frac{4R^2}{\alpha^2} + 4 \frac{2\mu R^2 \epsilon}{l^2}$$

$$= \frac{4R^2}{\alpha^2} \left(1 + \frac{2\mu \epsilon \alpha^2}{l^2} \right) = \frac{4R^2}{\alpha^2} \left(1 + \frac{2\mu \epsilon \alpha^2}{GM_\mu^2 \alpha} \right)$$

$$= \frac{4R^2}{\alpha^2} \left(1 + \frac{2\epsilon \alpha}{GM_\mu} \right) = \boxed{\frac{4R^2 \epsilon^2}{\alpha^2}}$$

where $e^2 = 1 + \frac{2E\alpha}{GM\mu} \geq 1$ (for scattering orbit)

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2

Thus, $\sqrt{-\Delta} = \frac{2Re}{\alpha}$

$$\rightarrow \phi_{min} = - \left[\arcsin \left(\frac{-2 + \frac{2R}{\alpha}}{\left(\frac{2Re}{\alpha}\right)} \right) - \arcsin \left(\frac{\frac{2R}{\alpha}}{\frac{2Re}{\alpha}} \right) \right]$$

$$= - \left[\arcsin \left(\frac{1 - \frac{\alpha}{R}}{e} \right) - \arcsin \left(\frac{1}{e} \right) \right]$$

$$= - \left[\arcsin \left(\frac{1 - \frac{\alpha}{R}}{e} \right) - \arcsin \left(\frac{1}{e} \right) \right]$$

where $R =$ closest approach for r .

$$= b \sqrt{\frac{e-1}{e+1}}$$

impact parameter

$$e^2 = 1 + \left(\frac{bV_{\infty}^2}{GM} \right)^2 \quad (\text{see below})$$

$$\rightarrow \frac{bV_{\infty}^2}{GM} = \sqrt{e^2 - 1}$$

$$E = \frac{1}{2} \mu V_{\infty}^2 \leftarrow \text{Newtonian}$$

$$l = \mu b V_{\infty}$$

$$\alpha = \frac{l^2}{GM\mu^2} = \frac{b^2 V_{\infty}^2}{GM}$$

$$\alpha = \frac{b^2 V_{\infty}^2}{GM}$$

~~XXXXXXXXXX~~

$$\rightarrow e^2 = 1 + \frac{\frac{1}{2} \mu V_{\infty}^2 \alpha}{GM\mu}$$

$$= 1 + \frac{V_{\infty}^2 \alpha}{GM}$$

$$= 1 + \frac{V_{\infty}^2 l^2}{GM GM \mu^2}$$

$$= 1 + \frac{V_{\infty}^2 \mu^2 b^2 V_{\infty}^2}{(GM)^2 \mu^2} = 1 + \left(\frac{bV_{\infty}^2}{GM} \right)^2$$

$$\begin{aligned}
 1 - \frac{\alpha}{R} &= 1 - \frac{\alpha}{b \sqrt{\frac{e-1}{e+1}}} = 1 - \left(\frac{\alpha}{b}\right) \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - \frac{b v_{\infty}^2}{GM} \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - \sqrt{e^2 - 1} \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - \sqrt{(e-1)(e+1)} \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - (e+1) \\
 &= -e
 \end{aligned}$$

$$\begin{aligned}
 \rightarrow \phi_{min} &= -\left[\arcsin(-1) - \arcsin\left(\frac{1}{e}\right)\right] \\
 &= -\left[-\frac{\pi}{2} - \arcsin\left(\frac{1}{e}\right)\right] \\
 &= \frac{\pi}{2} + \arcsin\left(\frac{1}{e}\right)
 \end{aligned}$$

$$2\phi_{min} = \pi + 2 \arcsin\left(\frac{1}{e}\right)$$

$$\gamma = \frac{1}{\sqrt{1 - (u/c)^2}}$$

$$\theta = 2\phi_{min} - \pi$$

$$= 2 \arcsin\left(\frac{1}{e}\right) \quad (\text{Deflection angle})$$

$$\frac{\theta}{2} = \arcsin\left(\frac{1}{e}\right)$$

$$\left(\frac{2}{\theta} = \frac{b v_{\infty}^2}{GM} \rightarrow \theta = \frac{2GM}{b v_{\infty}^2}\right)$$

$$\frac{1}{e} = \sin\left(\frac{\theta}{2}\right)$$

$$\text{Now, } \cot\left(\frac{\theta}{2}\right) = \sqrt{\csc^2\left(\frac{\theta}{2}\right) - 1} = \sqrt{\frac{1}{\sin^2\left(\frac{\theta}{2}\right)} - 1} = \sqrt{e^2 - 1} = \frac{b v_{\infty}^2}{GM}$$

Exercise 5.6 Gravitational differential cross section

$$a) \frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$\cot\left(\frac{\theta}{2}\right) = \frac{b v_{\infty}^2}{GM}$$

$$\rightarrow b = \frac{GM}{v_{\infty}^2} \cot\left(\frac{\theta}{2}\right)$$

$$\cot = \frac{\cos}{\sin}$$

$$\frac{db}{d\theta} = \frac{GM}{v_{\infty}^2} \frac{-\sin^2(\frac{\theta}{2}) \frac{1}{2} - \cos^2(\frac{\theta}{2}) \frac{1}{2}}{\sin^2(\frac{\theta}{2})}$$

$$= - \frac{GM}{2v_{\infty}^2} \frac{1}{\sin^2(\frac{\theta}{2})}$$

$$\text{Thus, } \frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$= \frac{\frac{GM}{v_{\infty}^2} \cot(\frac{\theta}{2})}{\sin\theta} \left(\frac{GM}{2v_{\infty}^2} \frac{1}{\sin^2(\frac{\theta}{2})} \right)$$

$$= \frac{G^2 M^2}{v_{\infty}^4} \frac{1}{2} \frac{\cancel{\cot(\frac{\theta}{2})}}{\cancel{\sin(\frac{\theta}{2})} \cancel{2\sin(\frac{\theta}{2})\cancel{\cot(\frac{\theta}{2})}}} \frac{1}{\sin^2(\frac{\theta}{2})}$$

$$= \frac{1}{4} \frac{G^2 M^2}{[v_{\infty} \sin(\frac{\theta}{2})]^4}$$

NOTE: $v_{\infty}^2 = \frac{2E}{m}$

$\rightarrow$

$$= \frac{G^2 M^2 m^2 \csc^4(\frac{\theta}{2})}{16 E^2} = \left(\frac{GMm}{4E} \right)^2 \csc^4(\frac{\theta}{2})$$

$$b) \quad \frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$= \frac{1}{2} \left| \frac{db^2}{d(\cos\theta)} \right|$$

$$c) \quad \tan\left(\frac{x}{2}\right) = \frac{\sin\left(\frac{x}{2}\right)}{\cos\left(\frac{x}{2}\right)}$$

$$\frac{\sin x}{1 + \cos x} = \frac{2 \sin\left(\frac{x}{2}\right) \cos\left(\frac{x}{2}\right)}{1 + \cos^2\left(\frac{x}{2}\right) - \sin^2\left(\frac{x}{2}\right)}$$

$$= \frac{\cancel{2} \sin\left(\frac{x}{2}\right) \cos\left(\frac{x}{2}\right)}{\cancel{2} \cos^2\left(\frac{x}{2}\right)}$$

$$= \frac{\sin\left(\frac{x}{2}\right)}{\cos\left(\frac{x}{2}\right)}$$

$$= \tan\left(\frac{x}{2}\right)$$

$$\text{further, } \cos\left(\frac{\theta}{2}\right) = \frac{bv_{\infty}^2}{GM} = \frac{1}{\tan\left(\frac{\theta}{2}\right)}$$

$$\frac{bv_{\infty}^2}{GM} = \frac{1 + \cos\theta}{\sin\theta}$$

$$\frac{b v_{\infty}^2}{G M} = \frac{1 + \cos \theta}{\sin \theta}$$

$$= \frac{1 + \cos \theta}{\sqrt{1 - \cos^2 \theta}}$$

$$= \sqrt{\frac{1 + \cos \theta}{1 - \cos \theta}}$$

$$\rightarrow \boxed{b^2 = \frac{G^2 M^2}{v_{\infty}^4} \left(\frac{1 + \cos \theta}{1 - \cos \theta} \right)}$$

Then,

$$\frac{1+x}{1-x}$$

$$\frac{d\sigma}{d\Omega} = \frac{1}{2} \left| \frac{db^2}{d(\cos \theta)} \right|$$

$$= \frac{1}{2} \frac{G^2 M^2}{v_{\infty}^4} \frac{(1 - \cancel{\cos \theta}) - (-1)(1 + \cancel{\cos \theta})}{(1 - \cos \theta)^2}$$

$$= \frac{1}{2} \frac{G^2 M^2}{v_{\infty}^4} \frac{2}{(1 - \cos \theta)^2}$$

$$= \frac{1}{2} \frac{G^2 M^2}{v_{\infty}^4} \frac{2}{(2 \sin^2(\frac{\theta}{2}))^2}$$

$$= \boxed{\frac{1}{4} \frac{G^2 M^2}{v_{\infty}^4} \frac{1}{\sin^4(\frac{\theta}{2})}}$$

$$\begin{aligned} \cos \theta &= \cos(2 \cdot \frac{\theta}{2}) \\ &= \cos^2(\frac{\theta}{2}) - \sin^2(\frac{\theta}{2}) \\ &= 1 - 2 \sin^2(\frac{\theta}{2}) \\ 2 \sin^2(\frac{\theta}{2}) &= 1 - \cos \theta \end{aligned}$$

Exercise:
5.7

Newtonian calculation for gravitational scattering:

$$\cot\left(\frac{\theta}{2}\right) = \frac{b v_\infty^2}{GM} \quad (5.32)$$

Suppose $\theta \ll 1$ (small deflection)

$$\text{Then } \cot\left(\frac{\theta}{2}\right) = \frac{\cos\left(\frac{\theta}{2}\right)}{\sin\left(\frac{\theta}{2}\right)} \approx \frac{1}{\left(\frac{\theta}{2}\right)} = \frac{2}{\theta}$$

$$\rightarrow \frac{2}{\theta} \approx \frac{b v_\infty^2}{GM}$$

$$\theta \approx \frac{2GM}{b v_\infty^2}$$

If we treat light as a Newtonian particle moving at $v_\infty = c$
then

$$\boxed{\theta \approx \frac{2GM}{bc^2}} \quad (\text{Newtonian})$$

compare to GR calculation:

$$\boxed{\theta \approx \frac{4GM}{bc^2}} \quad (\text{GR})$$

so off by a factor of 2.

problem (5.8)

Jupiter injection orbit

(1)

$$e^2 = 1 + \frac{2E\alpha}{GM_m}, \quad \alpha = a(1-e^2)$$



1) Circular orbit at r_{ES} around Sun;

$$e = 0, \quad \alpha = a_i = r_{ES} = 1 \text{ AU}$$

$$0 = 1 + \frac{2E_i a_i}{GM_m}$$

$$E_i = -\frac{GM_m}{2a_i} = -\frac{GM_m}{a_i} + \frac{1}{2} m v_i^2$$

2) In Jupiter injection orbit: $a_f = 3.15 \text{ AU}$

$$e = 0.683$$

$$e^2 - 1 = \frac{2E_f a_f (1-e^2)}{GM_m}$$

$$-\frac{GM_m}{2a_f} = E_f = -\frac{GM_m}{a_i} + \frac{1}{2} m v_f^2$$

$$\Delta E = E_f - E_i = -\frac{GM_m}{2} \left(\frac{1}{a_f} - \frac{1}{a_i} \right)$$

$$\Delta E = \frac{GM_m}{2} \left(\frac{a_f - a_i}{a_f a_i} \right) \approx \frac{GM_m}{2} \frac{\Delta a}{a_f a_i}$$

$$\Delta E = \frac{1}{2} m \Delta v^2 \rightarrow \frac{1}{2} m \Delta v^2 = \frac{GM_m}{2} \left(\frac{\Delta a}{a_f a_i} \right)$$

Solve for v_i, v_f :

$$- \frac{GM_m}{2a_i} = - \frac{GM_m}{a_i} + \frac{1}{2} m v_i^2$$

$$+ \frac{GM_m}{2a_i} = \frac{1}{2} m v_i^2$$

$$v_i = \sqrt{\frac{GM}{a_i}} = \boxed{3 \times 10^4 \text{ m/s}}$$

$$- \frac{GM_m}{2a_f} = - \frac{GM_m}{a_i} + \frac{1}{2} m v_f^2$$

$$GM \left(\frac{1}{a_i} - \frac{1}{2a_f} \right) = \frac{1}{2} v_f^2$$

$$\rightarrow v_f = \sqrt{2 GM \frac{2a_f - a_i}{2a_f a_i}}$$

$$= \sqrt{GM \left(\frac{2a_f - a_i}{a_f a_i} \right)}$$

$$= \sqrt{\frac{GM}{1 \text{ AU}} \left(\frac{6.3 - 1}{3.15} \right)}$$

$$= 3 \times 10^4 \text{ m/s} \cdot \sqrt{\frac{5.3}{3.15}}$$

$$= \boxed{3 \times 10^4 \frac{\text{m}}{\text{s}} (1.3)} \quad (30\% \text{ } 1.3 \text{ } 1.3 \text{ } 1.3)$$

$$\Delta V = v_f - v_i = 3 \times 10^4 \frac{\text{m}}{\text{s}} (1.3 - 1) = \boxed{9 \frac{\text{km}}{\text{s}}}$$

```
function deltaV = calBoost(a_i, a_f)
%
% calculate additional velocity needed to boost from
% elliptical orbit with semi-major axis a_i to an
% elliptical orbit with semi-major axis a_f, assuming
% both orbits have sun at one focal point
%
% input: a_i, a_f in units of AU
%
% example: calBoost(1, 3.15)
%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
% constants (MKS)
G = 6.67e-11;
M_sun = 2e30;
AU = 1.5e11;

% convert to MKS units
a_i = a_i*AU;
a_f = a_f*AU;

% calculate initial and final velocities and deltaV
v_i = sqrt(G*M_sun/a_i);
v_f = sqrt(2*G*M_sun*(1/a_i-1/(2*a_f)));
deltaV = v_f-v_i;

% display results
fprintf('v_i = %f km/s\n', v_i/1000);
fprintf('v_f = %f km/s\n', v_f/1000);
fprintf('deltaV = %f km/s\n', deltaV/1000);

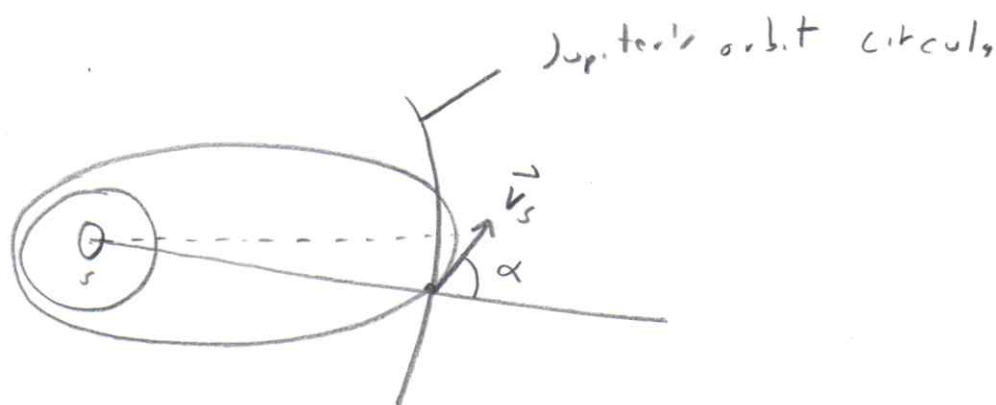
return
```

problem:

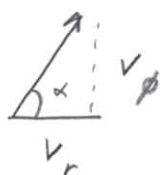
(5.9)

Calculate $\tan \alpha$ for Jupiter's gravitational slingshot maneuver

(1)



$$\tan \alpha = \frac{v_d}{v_r} = \frac{h d\phi/dt}{dr/dt} = \frac{r d\phi}{dr}$$



orbit equation: (ellipse)

$$r = \frac{a(1-e^2)}{1+e \cos \phi}$$

$$\rightarrow 1+e \cos \phi = \frac{a}{r} (1-e^2)$$

$$\cos \phi = \frac{\frac{a}{r} (1-e^2) - 1}{e}$$

$$\frac{dr}{d\phi} = \frac{-a(1-e^2)}{(1+e \cos \phi)^2} (-e \sin \phi)$$

$$= \frac{+ a e \sin \phi (1-e^2)}{(1+e \cos \phi)^2}$$

$$= \cancel{e \sin \phi} + \frac{e \sin \phi}{a(1-e^2)} \frac{a^2 (1-e^2)^2}{(1+e \cos \phi)^2}$$

$$= \frac{+ e \sin \phi}{a(1-e^2)} r^2$$

$$\begin{aligned}
 \sin \phi &= \sqrt{1 - \cos^2 \phi} \\
 &= \sqrt{1 - \frac{\left[\left(\frac{a}{r}\right)(1-e^2) - 1\right]^2}{e^2}} \\
 &= \frac{1}{e} \sqrt{e^2 - \left(\frac{a}{r}\right)^2 (1-e^2)^2 - 1 + 2\left(\frac{a}{r}\right)(1-e^2)} \\
 &= \frac{1}{e} \sqrt{(1-e^2) - \left(\frac{a}{r}\right)^2 (1-e^2)^2 + 2\left(\frac{a}{r}\right)(1-e^2)} \\
 &= \frac{1}{e} \sqrt{1-e^2} \sqrt{-1 - \left(\frac{a}{r}\right)^2 (1-e^2) + 2\left(\frac{a}{r}\right)}
 \end{aligned}$$

Thus, ~~the~~

$$\begin{aligned}
 \tan \alpha &= r \frac{d\phi}{dr} \\
 &= r \frac{a(1-e^2)}{e \sin \phi r^2} \\
 &= + \frac{1}{r} \frac{a(1-e^2)}{\sqrt{1-e^2} \sqrt{-1 - \left(\frac{a}{r}\right)^2 (1-e^2) + 2\left(\frac{a}{r}\right)}} \\
 &= + \frac{a}{r} \frac{\sqrt{1-e^2}}{\sqrt{-1 - \left(\frac{a}{r}\right)^2 (1-e^2) + 2\left(\frac{a}{r}\right)}} \\
 &= + \frac{a}{r} \frac{\sqrt{1-e^2}}{\left(\frac{a}{r}\right) \sqrt{-(1-e^2) - \left(\frac{r}{a}\right)^2 + 2\frac{r}{a}}}
 \end{aligned}$$

$$\cancel{\frac{1-e^2}{\left(\frac{a}{r}\right) \sqrt{-(1-e^2) - \left(\frac{r}{a}\right)^2 + 2\frac{r}{a}}}}$$

$$= \frac{\sqrt{1-e^2}}{\sqrt{-\left(\frac{r}{a}\right)^2 + 2\frac{r}{a} - 1 + e^2}}$$

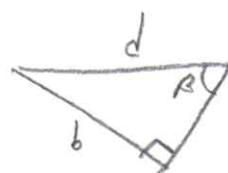
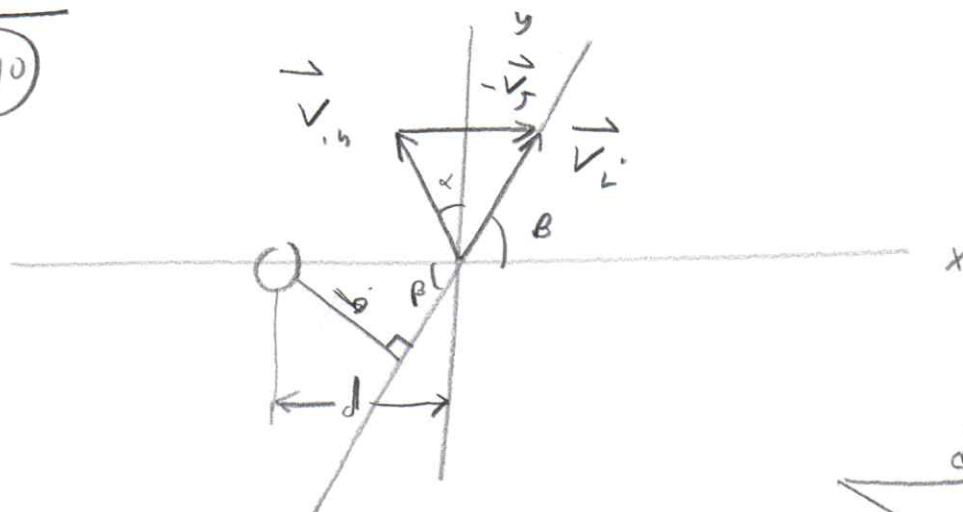
$$= \frac{\sqrt{1-e^2}}{\sqrt{e^2 - \left(1 - \left(\frac{r}{a}\right)\right)^2}}$$

Problem:

(5.10)

Velocities in co-moving reference frame

(1)



$$\vec{V}_i = \vec{V}_{in} - \vec{V}_J$$

$$\sin \beta = \frac{b}{d}$$

$$b = d \sin \beta$$

$$\vec{V}_{in} = -V_{in} \sin \alpha \hat{x} + V_{in} \cos \alpha \hat{y}$$

$$-\vec{V}_J = V_J \hat{x}$$

$$\vec{V}_i = V_i \cos \beta \hat{x} + V_i \sin \beta \hat{y}$$

$$\text{thus, } \tan \beta = \frac{\sin \beta}{\cos \beta}$$

$$= \frac{V_{i,y}}{V_{i,x}}$$

$$= \frac{V_{in,y} - V_{J,y}}{V_{in,x} - V_{J,x}}$$

$$= \frac{V_{in} \cos \alpha}{-V_{in} \sin \alpha + V_J}$$

Also, show $V_i^2 = V_{in}^2 + V_J^2 - 2 V_{in} V_J \sin \alpha$

Proof:

$$\begin{aligned} V_i^2 &= (V_{in,x} - V_{J,x})^2 + (V_{in,y} - V_{J,y})^2 \\ &= (-V_{in} \sin \alpha + V_J)^2 + (V_{in} \cos \alpha)^2 \\ &= \underbrace{V_{in}^2 \sin^2 \alpha + V_J^2 - 2 V_{in} V_J \sin \alpha + V_{in}^2 \cos^2 \alpha}_{} \\ &= V_{in}^2 + V_J^2 - 2 V_{in} V_J \sin \alpha \end{aligned}$$

Problem: (5.11) Determine final velocity for gravitational slingshot

$$\vec{V}_{out} = (v_i \cos(\theta + \beta) - v_J) \hat{x} + v_i \sin(\theta + \beta) \hat{y}$$

where $v_i^2 = v_{in}^2 + v_J^2 - 2 v_{in} v_J \cos \alpha$ (1)

$$\cot\left(\frac{\theta}{2}\right) = \frac{b v_i^2}{G M_J} \quad (2)$$

$$\tan \beta = \frac{v_{in} \cos \alpha}{v_J - v_{in} \sin \alpha} \quad (3)$$

$$\tan \alpha = \sqrt{\frac{1 - e^2}{e^2 - (1 - r/q)^2}} \quad (4) \text{ where } r = |\vec{r}_{JS}|$$

$$b = d \sin \beta \quad (5)$$

~~At~~ a, d, e : are initial conditions,

$$r_a = 5.3 \text{ AU}, \quad r_p = 1 \text{ AU} \rightarrow \begin{aligned} a &= 3.15 \text{ AU} \\ e &= 0.683 \end{aligned}$$

★ Actually take r_a, r_p, d as input

Need v_{in} :

initial velocity of spacecraft
before scattering.

(2)

$$E = - \frac{GM_{\odot} m_s}{2a}$$

3.15 AU for Jupiter
injection
orbit

$$-\frac{GM_{\odot} m_s}{2a} = -\frac{GM_{\odot} m_s}{r_{JS}} + \frac{1}{2} m_s v_{in}^2$$

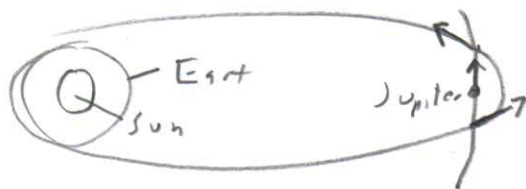
5.2 AU



$$v_{in} = \sqrt{2 \left(-\frac{GM_{\odot}}{2a} + \frac{GM_{\odot}}{r_{JS}} \right)}$$

$$= \sqrt{2 GM_{\odot} \left(\frac{1}{r_{JS}} - \frac{1}{2a} \right)}$$

To determine final ~~ap~~ aphelion distance:



Scatters out at $r_{JS} = 5.2 \text{ AU} \equiv q_i$
 with v_{out}

$$E = - \frac{GM}{2a_f} = - \frac{GM}{a_i} + \frac{1}{2} v_{out}^2$$

$\uparrow$
 5.2 AU

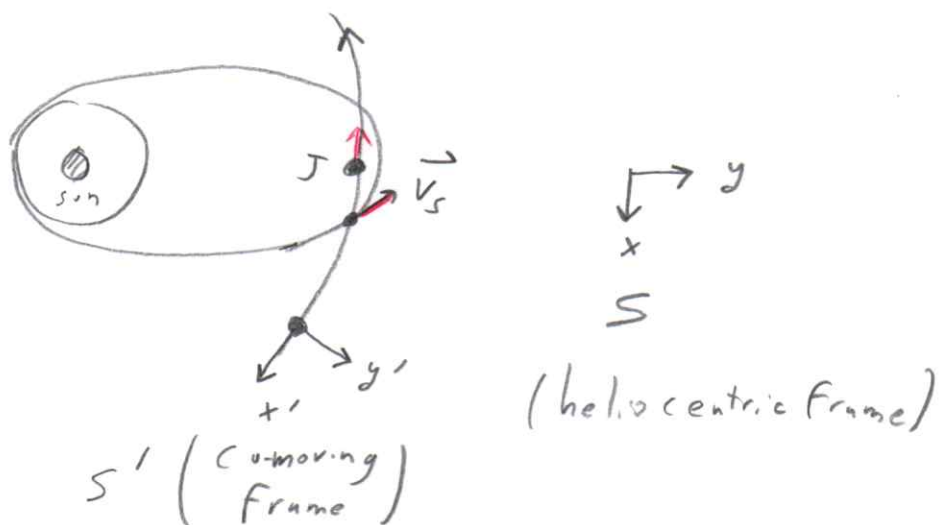
$$- \frac{GM}{2a_f} = - \frac{GM}{a_i} + \frac{1}{2} v_{out}^2$$

$$- \frac{GM}{2} \frac{1}{\left(- \frac{GM}{a_i} + \frac{1}{2} v_{out}^2 \right)} = a_f$$

$\swarrow$ solve mult

$$a_f = \frac{-GM/2}{\left(-GM/a_i + \frac{1}{2} v_{out}^2 \right)}$$

$\swarrow$ r_{JS}



$$\vec{V}_{out} = \vec{V}_o + \vec{V}_J$$

$$= v_i \cos(\theta + \beta) \hat{x} + v_i \sin(\theta + \beta) \hat{y}$$

$$\quad \quad \quad - v_J \hat{x}$$

$$= [v_i \cos(\theta + \beta) - v_J] \hat{x} + v_i \sin(\theta + \beta) \hat{y}$$

```

function jupiterScatter(r_p, r_a, d)
%
% inputs:
% r_perihelion, r_aphelion, in units of AU
% d: distance from Jupiter in units of Jupiter radius R_J
%
% e.g., jupiterScatter(1, 5.3, 10)
%
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%

% constants (MKS)
G = 6.67e-11;
M_sun = 2e30;
M_J = 1.9e27;
AU = 1.5e11;
R_J = 7e7; % mean radius jupiter
r_JS = 5.2*AU; % mean orbital radius of jupiter

% convert to MKS units
r_p = r_p*AU;
r_a = r_a*AU;
d = d*R_J;

% calculate a and e from r_p, r_a
a = 0.5*(r_p+r_a);
e = 0.5*(r_a-r_p)/a;

% calculate initial velocity of spacecraft (v_infinity)
v_in = sqrt(2*G*M_sun*(1/r_JS-1/(2*a)));

% calculate orbital velocity of jupiter
v_J = sqrt(G*M_sun/r_JS);

% calculate angles (radians)
alpha = atan(sqrt((1-e^2)/(e^2 - (1-r_JS/a)^2)));
beta = atan(v_in * cos(alpha)/(v_J - v_in*sin(alpha)));
b = d*sin(beta);
v_i = sqrt(v_in^2 + v_J^2 - 2*v_in*v_J*sin(alpha));
theta = 2*acot(b*v_i^2/(G*M_J));
v_out = sqrt((v_i*cos(theta+beta) - v_J)^2 + (v_i*sin(theta+beta))^2);
phi_out = atan2(v_i*sin(theta+beta), v_i*cos(theta+beta) - v_J);

% calculate aphelion of scattered orbit
a_f = (-G*M_sun/2)/(-G*M_sun/r_JS + 0.5*v_out^2);
if a_f<0
    a_f = inf;
    display(' ')
    display('spacecraft ejected out of solar system!')
end

% display results
fprintf('\n')
fprintf('v_in = %f km/s\n', v_in/1000);
fprintf('v_out = %f km/s\n', v_out/1000);
fprintf('phi_out = %f degree\n', phi_out*180/pi);
fprintf('aphelion = %f AU\n', a_f/AU);

```

```
fprintf('v_J   = %f km/s\n', v_J/1000);  
fprintf('v_i   = %f km/s\n', v_i/1000);  
fprintf('alpha = %f degree\n', alpha*180/pi);  
fprintf('beta  = %f degree\n', beta*180/pi);  
fprintf('theta = %f degree\n', theta*180/pi);  
fprintf('b = %f R_J\n', b/R_J);
```

```
return
```



```
>> jupiterScatter(1, 5.3, 1000)
```

```
v_in = 7.728081 km/s  
v_out = 9.006630 km/s  
phi_out = 156.458064 degree  
aphelion = 3.408297 AU  
v_J = 13.077677 km/s  
v_i = 6.015025 km/s  
alpha = 74.277803 degree  
beta = 20.373932 degree  
theta = 16.358148 degree  
b = 348.145573 R_J
```

```
>> jupiterScatter(1, 5.3, 100)
```

```
v_in = 7.728081 km/s  
v_out = 17.602089 km/s  
phi_out = 164.989016 degree  
aphelion = 27.603841 AU  
v_J = 13.077677 km/s  
v_i = 6.015025 km/s  
alpha = 74.277803 degree  
beta = 20.373932 degree  
theta = 110.343328 degree  
b = 34.814557 R_J
```

```
>> jupiterScatter(1, 5.3, 10)
```

spacecraft ejected out of solar system!

```
v_in = 7.728081 km/s  
v_out = 18.996130 km/s  
phi_out = -176.096827 degree  
aphelion = Inf AU  
v_J = 13.077677 km/s  
v_i = 6.015025 km/s  
alpha = 74.277803 degree  
beta = 20.373932 degree  
theta = 172.040099 degree  
b = 3.481456 R_J
```

Problem: Differential cross section for equal-mass particles
in the lab frame

(5.12)

$$\left(\frac{d\sigma}{d\Omega} \right)' = \left(\frac{d\sigma}{d\Omega} \right) \left| \frac{d(\cos\theta)}{d(\cos\psi)} \right|$$

$$= \left(\frac{d\sigma}{d\Omega} \right) \left| \frac{d(\cos\theta)}{d(\cos(\frac{\theta}{2}))} \right|$$

$$\psi = \frac{\theta}{2}$$

$$= \left(\frac{d\sigma}{d\Omega} \right) \left| \frac{\sin\theta d\theta}{\sin(\frac{\theta}{2}) \frac{1}{2} d\theta} \right|$$

$$= \left(\frac{d\sigma}{d\Omega} \right) \frac{2\sin(2\psi)}{\sin\psi}$$

$$= \left(\frac{d\sigma}{d\Omega} \right) \frac{4\cancel{\sin\psi} \cos\psi}{\cancel{\sin\psi}}$$

$$= 4 \cos\psi \left(\frac{d\sigma}{d\Omega} \right)$$

~~Problem~~: Calculate $\cot(\frac{\theta}{2})$ for Rutherford scattering.

OLD!

For gravitational scattering:

$$\cot\left(\frac{\theta}{2}\right) = \frac{bv_a^2}{GM}$$

Reexpress RHS in terms of E , kQ_2 using

$$GM_M \leftrightarrow kQ_2$$

$$E = \frac{1}{2}mv_a^2$$

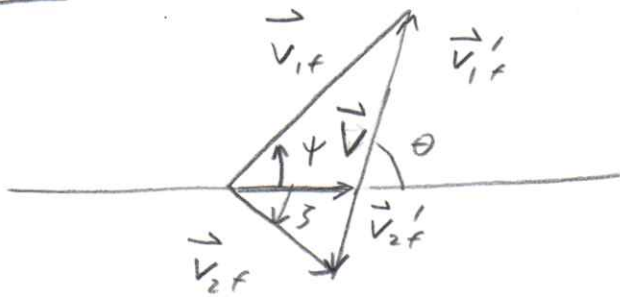
$$\rightarrow v_a^2 = \frac{2E}{m}$$

$$\text{Thus, } \cot\left(\frac{\theta}{2}\right) = \frac{b}{GM} \frac{2E}{m}$$

$$= \frac{2Eb}{kQ_2}$$

Problem: 5.13 Verify expression for $\cos \delta$

ans



$$V_{2f} \cos \delta = V - V_{2f}' \cos \theta$$

$$V_{2f} \sin \delta = V_{2f}' \sin \theta$$

Square and add:

$$V_{2f}^2 \cos^2 \delta + V_{2f}^2 \sin^2 \delta$$

$$= (V - V_{2f}' \cos \theta)^2 + (V_{2f}' \sin \theta)^2$$

$$= V^2 + (V_{2f}')^2 \cos^2 \theta - 2V V_{2f}' \cos \theta + (V_{2f}')^2 \sin^2 \theta$$

$$= (V_{2f}')^2$$

$$= V^2 - 2V V_{2f}' \cos \theta + (V_{2f}')^2$$

Thus, $V_{2f}^2 = V^2 - 2V V_{2f}' \cos \theta + (V_{2f}')^2$

substitute back into $\cos \delta$ equation:

$$\cos \delta = \frac{V - V_{2f}' \cos \theta}{\sqrt{V^2 - 2V V_{2f}' \cos \theta + (V_{2f}')^2}}$$

Divide by v_{zf}' :

$$\begin{aligned} (0) \beta &= \frac{\frac{V}{v_{zf}'} - \cos \theta}{\sqrt{\left(\frac{V}{v_{zf}'}\right)^2 - 2\left(\frac{V}{v_{zf}'}\right)\cos \theta + 1}} \\ &= \frac{\beta_2 - \cos \theta}{\sqrt{\beta_2^2 - 2\beta_2\cos \theta + 1}} \end{aligned}$$

$$, \beta_2 = \frac{V}{v_{zf}'}$$

Problem: Verify

OLD

$$\left(\frac{d\sigma}{dn}\right)' = \frac{(1 + 2\rho \cos \theta + \rho^2)^{3/2}}{1 + \rho \cos \theta} \left(\frac{d\sigma}{dn}\right)$$

Proof: $\left(\frac{d\sigma}{dn}\right)' = \left(\frac{d\sigma}{dn}\right) \left| \frac{d \cos \theta}{d \cos \psi} \right|$

Now: $\cos \psi = \frac{\cos \theta + \rho}{\sqrt{1 + 2\rho \cos \theta + \rho^2}}$

$$d(\cos \psi) = \frac{d(\cos \theta) \sqrt{1 + 2\rho \cos \theta + \rho^2} - \frac{1}{\sqrt{1 + 2\rho \cos \theta + \rho^2}} \rho d(\cos \theta) (\cos \theta + \rho)}{1 + 2\rho \cos \theta + \rho^2}$$

$$= \frac{d(\cos \theta)}{[1 + 2\rho \cos \theta + \rho^2]^{3/2}} \left\{ (1 + 2\rho \cos \theta + \rho^2) - \rho (\cos \theta + \rho) \right\}$$

$$= \frac{d(\cos \theta) [1 + \rho \cos \theta]}{[1 + 2\rho \cos \theta + \rho^2]^{3/2}}$$

Thus, $\boxed{\frac{d(\cos \theta)}{d(\cos \psi)} = \frac{[1 + 2\rho \cos \theta + \rho^2]^{3/2}}{1 + \rho \cos \theta}}$

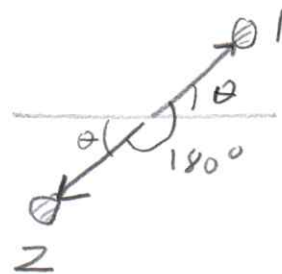
Problem:

OLD

Scattering of equal-mass hard spheres in the lab frame.

In COM frame:

$$\vec{v}_1' = -\vec{v}_2'$$



In lab frame:

$$\vec{v}_1 = \vec{V} + \vec{v}_1'$$

$$\vec{v}_2 = \vec{V} + \vec{v}_2' = \vec{V} - \vec{v}_1'$$

Then,

$$\begin{aligned}\vec{v}_1 \cdot \vec{v}_2 &= (\vec{V} + \vec{v}_1') \cdot (\vec{V} - \vec{v}_1') \\ &= V^2 - v_1'^2\end{aligned}$$

But: $V = \frac{1}{2} V_{\infty}$ ← (for equal mass)
 $v_1' = \frac{1}{2} V_{\infty}$ ←

so $\boxed{\vec{v}_1' \cdot \vec{v}_2 = 0}$

Problem: Principle of relativity for elastic collisions

(5.1)

For an elastic collision, total KE is conserved

$$\text{i.e., } \sum_I \frac{1}{2} m_I v_{Ii}^2 = \sum_I \frac{1}{2} m_I v_{If}^2$$

(before) (after)

By the principle of relativity, this must hold in all inertial reference frames.

Let S, S' denote two inertial frames related by $\vec{u}$

$$\begin{array}{c} \diagup \\ S \end{array} \quad \begin{array}{c} \diagup \\ S \end{array} \rightarrow \vec{u} \quad \text{so} \quad \vec{v}' = \vec{v} - \vec{u}$$

$$\text{Then } \vec{v}'_{Ii} = \vec{v}_{Ii} - \vec{u}$$

$$\vec{v}'_{If} = \vec{v}_{If} - \vec{u}$$

In S' (cons. of total KE):

$$\sum_I \frac{1}{2} m_I v_{Ii}'^2 = \sum_I \frac{1}{2} m_I v_{If}'^2$$

$$\text{LHS} = \sum_I \frac{1}{2} m_I (\vec{v}_{Ii} - \vec{u}) \cdot (\vec{v}_{Ii} - \vec{u})$$

$$= \sum_I \frac{1}{2} m_I (v_{Ii}^2 + u^2 - \vec{u} \cdot \vec{v}_{Ii})$$

$$\text{RHS} = \sum_I \frac{1}{2} m_I (v_{If}^2 + u^2 - \vec{u} \cdot \vec{v}_{If})$$

Thus,

$$\sum_I \frac{1}{2} m_I v_{Ii}^2 + \frac{1}{2} M u^2 - \frac{1}{2} \vec{u} \cdot \sum_I m_I \vec{v}_{Ii}$$

$$= \sum_I \frac{1}{2} m_I v_{If}^2 + \frac{1}{2} M u^2 - \frac{1}{2} \vec{u} \cdot \sum_I m_I \vec{v}_{If}$$

$$\text{This} \rightarrow 0 = \vec{u} \cdot \left(\sum_I m_I \vec{v}_{Ii} - \sum_I m_I \vec{v}_{If} \right)$$

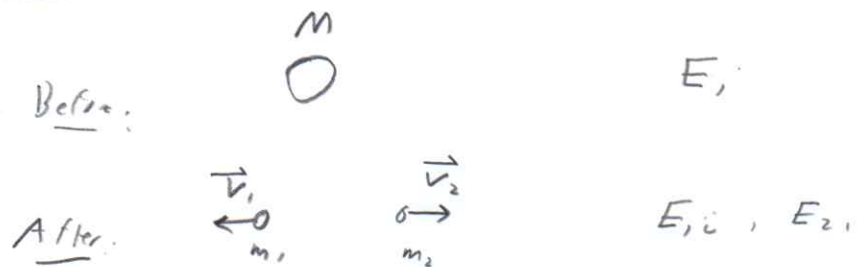
since $\vec{u}$ is arbitrary

$$\sum_I m_I \vec{v}_{Ii} = \sum_I m_I \vec{v}_{If} \quad \left(\text{cons. of total linear momentum} \right)$$

Prob (5.2) Disintegration of a particle of mass M into two constituent particles, mass m_1 and m_2 . (1)

~~Determine~~ Assume internal energy of original particle is ~~E_i~~ E_i and internal energies of constituent particles is E_{1i} , E_{2i} .

Determine velocities of constituent particles.



Conservation ~~of~~ of mass and total energy in Newtonian physics. [In SR, total relativistic momentum and total energy are ^{always} conserved. Total mass only conserved for elastic collisions.]

Now, $m_1 v_1 = m_2 v_2 \equiv p_0$ (cons of momentum)

$$E_i = E_{1i} + \frac{1}{2} m_1 v_1^2 + E_{2i} + \frac{1}{2} m_2 v_2^2 \quad (\text{cons of total energy})$$

$$\Delta E_i \equiv E_i - E_{1i} - E_{2i} = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

$$\boxed{\Delta E_i = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2}$$

$$\boxed{m_1 v_1 = m_2 v_2}$$

$$\begin{aligned} \text{Thus, } \Delta E_i &= \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 \left(\frac{m_1 v_1}{m_2} \right)^2 \\ &= \frac{1}{2} m_1 v_1^2 + \frac{1}{2} \frac{m_1^2}{m_2} v_1^2 \\ &= \frac{1}{2} m_1 v_1^2 \left(1 + \frac{m_1}{m_2} \right) \\ &= \frac{1}{2} m_1 v_1^2 \frac{M}{m_2} \end{aligned}$$

Also:

$$\begin{aligned}
 \Delta E_i &= \frac{1}{2} m_1 \left(\frac{m_2 v_2}{m_1} \right)^2 \frac{M}{m_2} \\
 &= \frac{1}{2} \frac{m_2^2}{m_1} v_2^2 \frac{M}{m_2} \\
 &= \frac{1}{2} m_2 v_2^2 \left(\frac{M}{m_1} \right)
 \end{aligned}$$

Reduced mass:

$$\mu = \frac{m_1 m_2}{M}$$

$$\begin{aligned}
 \Delta E_i &= \frac{1}{2} m_1^2 v_1^2 \left(\frac{M}{m_1 m_2} \right) \\
 &= \frac{1}{2} \frac{p_0^2}{M} \quad (\text{same for 2nd particle})
 \end{aligned}$$

~~$$\begin{aligned}
 &= \frac{1}{2} \frac{p_0^2}{M} \\
 &= \frac{1}{2} \frac{p_0^2}{M}
 \end{aligned}$$~~

$$\Delta E_i = \frac{1}{2} \frac{m_1^2 v_1^2}{\mu}$$

$$\frac{2\mu \Delta E_i}{m_1^2} = v_1^2$$

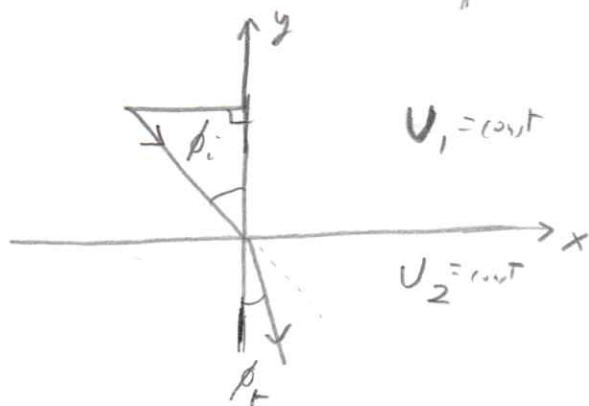
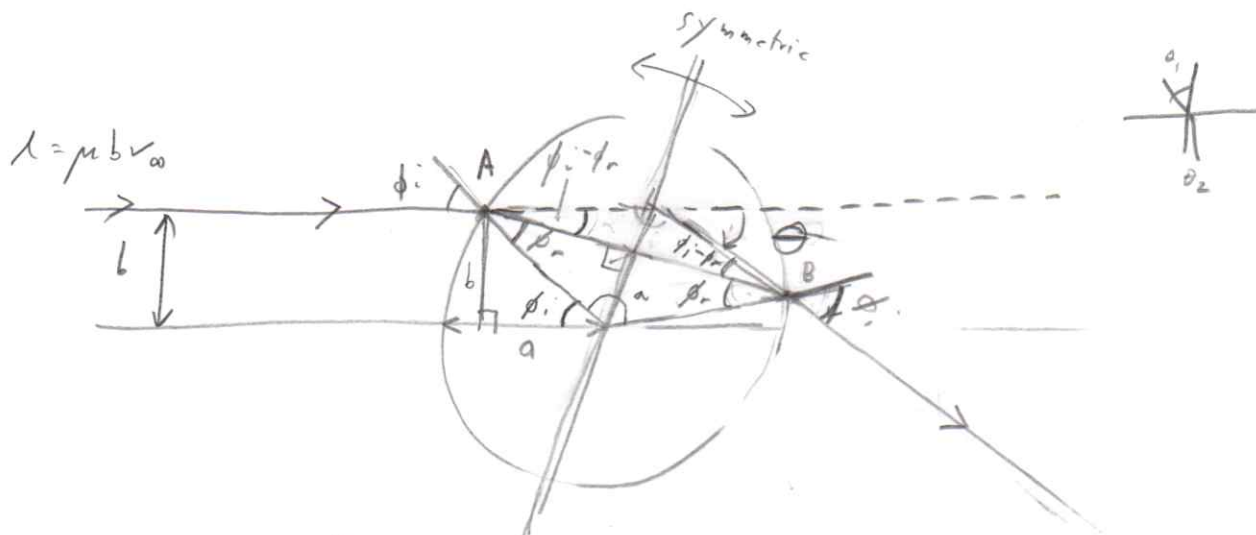
$$\begin{aligned}
 v_1 &= \sqrt{\frac{2\mu \Delta E_i}{m_1}} \\
 v_2 &= \sqrt{\frac{2\mu \Delta E_i}{m_2}}
 \end{aligned}$$

5.5 and 5.3

1

Problem Scattering off of spherical potential well

$$U(r) = \begin{cases} -U_0 & 0 \leq r \leq a \\ 0 & r > a \end{cases}$$



$$U_1 = \text{const}$$

$$E_1 = E_2 = E$$

$$E = \frac{1}{2} \mu (\dot{x}_1^2 + \dot{y}_1^2) + U_1$$

$$= \frac{1}{2} \mu (\dot{x}_2^2 + \dot{y}_2^2) + U_2$$

$$\frac{1}{2} \mu v_1^2 + U_1 = \frac{1}{2} \mu v_2^2 + U_2$$

$$v_2^2 - v_1^2 = \frac{2(U_1 - U_2)}{\mu}$$

cons. of energy

~~$$\frac{1}{2} \mu (\dot{x}_1^2 + \dot{y}_1^2) - \frac{1}{2} \mu (\dot{x}_2^2 + \dot{y}_2^2) = \frac{2(U_1 - U_2)}{\mu}$$~~

~~$$\dot{x}_2^2 - \dot{x}_1^2 + \dot{y}_2^2 - \dot{y}_1^2 = \frac{2(U_1 - U_2)}{\mu}$$~~

Now

$$\sin \phi_i = \frac{\dot{x}_1}{v_1}, \quad \sin \phi_r = \frac{\dot{x}_2}{v_2}$$

$$\text{But } \dot{x}_1 = \dot{x}_2$$

$$\text{so } v_1 \sin \phi_i = v_2 \sin \phi_r$$

cons. of momentum in x-direction

$$\mu \dot{x}_2 = \mu \dot{x}_1$$

(momentum unchanged in x-direction)

~~$$\tan \phi_i = \frac{\dot{y}_1}{\dot{x}_1}$$~~

~~$$\tan \phi_r = \frac{\dot{y}_2}{\dot{x}_2} = \frac{\dot{y}_1}{\dot{x}_1}$$~~

~~$$\text{thus } \dot{y}_1 \tan \phi_i = \dot{y}_2 \tan \phi_r$$~~

Thus, $v_1 \sin \phi_i = v_2 \sin \phi_r$
 $v_2^2 - v_1^2 = \frac{2}{n} (U_1 - U_2)$

* $\sin \phi_i = \frac{v_2}{v_1} \sin \phi_r$
 $= \frac{\sqrt{v_1^2 + \frac{2}{n}(U_1 - U_2)}}{v_1} \sin \phi_r$
 $= \sqrt{1 + \frac{2}{n v_1^2} (U_1 - U_2)} \sin \phi_r$

Thus, $\boxed{n = \sqrt{1 + \frac{2(U_1 - U_2)}{n v_1^2}}}$, $\boxed{\sin \phi_i = n \sin \phi_r}$



For $U_1 = 0$, $U_2 = -U_0$
 (at A):

$$n = \sqrt{1 + \frac{2(0 - (-U_0))}{m v_\infty^2}}$$

$$= \sqrt{1 + \frac{2U_0}{m v_\infty^2}} > 1$$

Geometry: $2\phi_r + \alpha = \pi$

$$2(\phi_i - \phi_r) + \beta = \pi$$

$$\theta + \beta = \pi$$

Thus, $\boxed{\theta = 2(\phi_i - \phi_r)}$

$\rightarrow$ ~~$\phi_r = \phi_i - \frac{\theta}{2}$~~

Also, $\boxed{\sin \phi_i = \frac{b}{a}}$

$\boxed{\phi_r = \phi_i - \frac{\theta}{2}}$

$$\text{So } \phi_r = \phi_i - \frac{\theta}{2}$$

$$\begin{aligned} \frac{1}{h} &= \frac{\sin \phi_r}{\sin \phi_i} = \frac{\sin(\phi_i - \frac{\theta}{2})}{\frac{b}{a}} \\ &= \frac{a}{b} \left(\sin \phi_i \cos\left(\frac{\theta}{2}\right) + \cos \phi_i \sin\left(\frac{\theta}{2}\right) \right) \\ &= \frac{a}{b} \left[\frac{b}{a} \cos\left(\frac{\theta}{2}\right) + \sqrt{1 - \left(\frac{b}{a}\right)^2} \sin\left(\frac{\theta}{2}\right) \right] \\ &= \cos\left(\frac{\theta}{2}\right) + \frac{a}{b} \sqrt{1 - \left(\frac{b}{a}\right)^2} \sin\left(\frac{\theta}{2}\right) \\ &= \cos\left(\frac{\theta}{2}\right) + \sqrt{\left(\frac{a}{b}\right)^2 - 1} \sin\left(\frac{\theta}{2}\right) \end{aligned}$$

$$\begin{aligned} \frac{1}{h} &= \cos\left(\frac{\theta}{2}\right) + \sqrt{\left(\frac{a}{b}\right)^2 - 1} \sin\left(\frac{\theta}{2}\right) \\ \left(\frac{\frac{1}{h} - \cos\left(\frac{\theta}{2}\right)}{\sin\left(\frac{\theta}{2}\right)} \right)^2 &= \left(\frac{a}{b} \right)^2 - 1 \\ \left(\frac{1 - n \cos(\theta/2)}{n \sin(\theta/2)} \right)^2 + 1 &= \left(\frac{a}{b} \right)^2 \\ \frac{(1 - n \cos(\theta/2))^2 + n^2 \sin^2(\theta/2)}{n^2 \sin^2(\theta/2)} &= \left(\frac{a}{b} \right)^2 \end{aligned}$$

Numerator:

$$\begin{aligned} &1 + n^2 \cos^2(\theta/2) - 2n \cos(\theta/2) + n^2 \sin^2(\theta/2) \\ &= 1 + n^2 - 2n \cos(\theta/2) \end{aligned}$$

Thou,

$$\left(\frac{a}{b}\right)^2 = \frac{1 - 2n \cos(\theta/2) + n^2}{n^2 \sin^2(\theta/2)}$$

$$\frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

Differentiate:

 b^{-2}

$$-2 \frac{a^2}{b^3} \left(\frac{db}{d\theta} \right) = \frac{\frac{2n}{2} \sin(\frac{\theta}{2})}{n^2 \sin^2(\frac{\theta}{2})} - \frac{\frac{2n^2 \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2})}{2} (1 - 2n \cos(\frac{\theta}{2}) + n^2)}{n^4 \sin^4(\frac{\theta}{2})}$$

$$-2 \left(\frac{a^2}{b^3} \right) \frac{1}{b} \frac{db}{d\theta} = \frac{\cancel{n^2} \sin^2(\frac{\theta}{2}) - \cancel{n^2} \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) (1 - 2n \cos(\frac{\theta}{2}) + n^2)}{n^2 \cancel{n^4} \sin^4(\frac{\theta}{2})}$$

$$\Rightarrow \frac{1}{b} \left(\frac{db}{d\theta} \right) = -\frac{1}{2} \left(\frac{b}{a} \right)^2 \frac{n \sin^2(\frac{\theta}{2}) - \cos(\frac{\theta}{2}) (1 - 2n \cos(\frac{\theta}{2}) + n^2)}{n^2 \sin^3(\frac{\theta}{2})}$$

$$= -\frac{1}{2} \frac{\cancel{n^2} \sin^2(\frac{\theta}{2})}{(1 - 2n \cos(\frac{\theta}{2}) + n^2)} \frac{\sin^2(\frac{\theta}{2}) - \cos(\frac{\theta}{2}) (1 - 2n \cos(\frac{\theta}{2}) + n^2)}{\cancel{n^2} \sin^3(\frac{\theta}{2})}$$

$$= -\frac{1}{2} \frac{n \sin^4(\frac{\theta}{2}) - \cos(\frac{\theta}{2}) (1 - 2n \cos(\frac{\theta}{2}) + n^2)}{\sin^4(\frac{\theta}{2}) (1 - 2n \cos(\frac{\theta}{2}) + n^2)}$$

$$\frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$= \frac{1}{2 \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2})} b^2 \left| \frac{db}{d\theta} \right|$$

$$\sin(2\theta) = 2 \sin\theta \cos\theta$$

$$= \frac{1}{2 \cancel{\cos(\theta)}} \frac{a^2 n^2 \cancel{\cos^2(\theta)}}{(1 - 2n \cos(\theta) + n^2)} \frac{1}{2} \left| \frac{n \sin^2(\theta) - \cos(\theta) (1 - 2n \cos(\theta) + n^2)}{\cancel{\cos(\theta)} (1 - 2n \cos(\theta) + n^2)} \right|$$

$$= \frac{\cancel{a^2} n^2}{4 \cos(\theta)} \frac{|n \sin^2(\theta) - \cos(\theta) (1 - 2n \cos(\theta) + n^2)|}{(1 - 2n \cos(\theta) + n^2)^2}$$

Numerator: $|n \sin^2(\theta) - \cos(\theta) (1 - 2n \cos(\theta) + n^2)|$

$$= |n \sin^2(\theta) - \cos(\theta) + 2n \cos^2(\theta) - n^2 \cos(\theta)|$$

$$= |n(1 - \cos^2(\theta)) - \cos(\theta) + 2n \cos^2(\theta) - n^2 \cos(\theta)|$$

$$= |n - n \cos^2(\theta) - \cos(\theta) + 2n \cos^2(\theta) - n^2 \cos(\theta)|$$

$$= |n - \cos(\theta) + n \cos^2(\theta) - n^2 \cos(\theta)|$$

$$= |(n - \cos(\theta)) + n \cos(\theta) (n - \cos(\theta))|$$

$$= |(n - \cos(\theta)) (1 + n \cos(\theta))|$$

$$= \cancel{n \cos(\theta)}$$

$$= |(n \cos(\frac{\theta}{2}) - 1) (n - \cos(\frac{\theta}{2}))|$$

$$\frac{d\sigma}{d\Omega} = \frac{a^2 n^2}{4 \cos(\frac{\theta}{2})} \frac{\cancel{(n \cos(\frac{\theta}{2}) - 1) (n - \cos(\frac{\theta}{2}))}}{(1 - 2n \cos(\theta) + n^2)^2}$$

what is maximum θ ?

$$\left(\frac{a}{b}\right)^2 = \frac{1 - 2n \cos(\theta/2) + n^2}{n^2 \sin^2(\theta/2)}$$

$$b = b(\theta) \leftrightarrow \theta = \theta(b)$$

want to set $0 = \frac{d\theta}{db}$

Differentiate w.r.t b :

$$-\frac{2a^2}{b^3} = \frac{\cancel{\frac{1}{b^2}} n \sin(\frac{\theta}{2}) \frac{d\theta}{db} n^2 \sin^2(\frac{\theta}{2}) - \cancel{2} n^2 \cancel{\frac{1}{b^2}} \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) \frac{d\theta}{db}}{n^4 \sin^4(\frac{\theta}{2})} \uparrow$$

$(1 - 2n \cos(\frac{\theta}{2}) + n^2)$

$$= \frac{\left[n^3 \sin^3(\frac{\theta}{2}) - n^2 \sin(\frac{\theta}{2}) \cos(\frac{\theta}{2}) (1 - 2n \cos(\frac{\theta}{2}) + n^2) \right] \frac{d\theta}{db}}{n^4 \sin^4(\frac{\theta}{2})}$$

get same expression for $\frac{db}{d\theta}$ as before.

$$\left[\text{recall } \frac{d\theta}{db} = \frac{1}{\left(\frac{db}{d\theta}\right)} \right]$$

obviously: $b \leq a$

$$b = 0 \rightarrow \theta = 0$$

$$b = a \rightarrow 1 = \frac{1 - 2n \cos(\theta/2) + n^2}{n^2 \sin^2(\theta/2)}$$

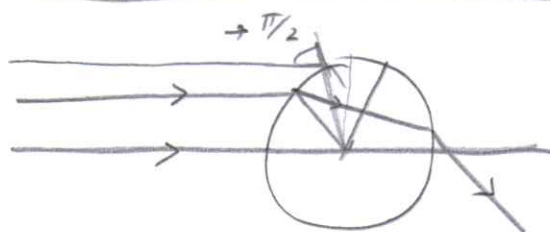
$$n^2 \sin^2(\theta/2) = 1 - 2n \cos(\theta/2) + n^2$$

$$\begin{aligned} \sigma &= 1 - 2n \cos(\theta/2) + n^2 / (1 - \sin^2(\theta/2)) \\ &= 1 - 2n \cos(\theta/2) + n^2 \sec^2(\theta/2) \\ &= \left(1 - n \cos(\theta/2)\right)^2 \end{aligned}$$

Thus, $\cos(\theta/2) = \frac{1}{n}$

$\cos\left(\frac{\theta_{\max}}{2}\right) = \frac{1}{n}$

 $\leftarrow \text{max deflection angle}$



$\sin \phi_i = \frac{b}{a}$

$b=a \rightarrow \phi_i = \pi/2$

$\rightarrow \sin \phi_i = n \sin \phi_r$

$1 = n \sin \phi_r$

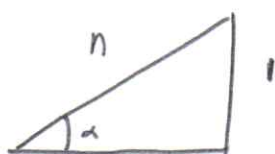
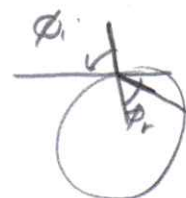
$\frac{1}{n} = \sin \phi_r$



$\theta = 2(\phi_i - \phi_r) = 2\left(\frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right)\right)$

$= \pi - 2 \arcsin\left(\frac{1}{n}\right)$

$\frac{\theta}{2} = \frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right) \rightarrow \cos\left(\frac{\theta}{2}\right) = \cos\left(\frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right)\right)$



$\sin \alpha =$

$$\begin{aligned} &= \cos\left(\frac{\pi}{2}\right) \cos\left(\arcsin\left(\frac{1}{n}\right)\right) + \underbrace{\sin\left(\frac{\pi}{2}\right)}_{=1} \sin\left(\arcsin\left(\frac{1}{n}\right)\right) \\ &= \frac{1}{n} \end{aligned}$$

$n = \sqrt{2}$

So $\boxed{\cos\left(\frac{\theta}{2}\right) = \frac{1}{n}}$ when $b=a$.

Total cross section:

$$\sigma_T = \pi a^2 \quad (\text{obvious since no scattering for } b > a)$$

check by integrating:

$$\sigma_T = \int_{\theta_{min}} \left(\frac{d\sigma}{d\Omega} \right) d\Omega, \quad d\Omega = 2\pi \sin\theta d\theta$$

$$= 2\pi \int_0^{2 \arccos(1/n)} d\theta \sin\theta \left(\frac{d\sigma}{d\Omega} \right)$$

$$= 2\pi \int_0^{2 \arccos(1/n)} d\theta \sin\theta$$

$$= \frac{\pi a^2 n^2}{\cancel{4}} \int_0^{2 \arccos(1/n)} d\theta \frac{\cancel{\sin(\theta/2)} \cancel{\cos(\theta/2)}}{\cancel{\cos(\theta/2)}} \frac{(n \cos(\theta/2) - 1)(n - \cos(\theta/2))}{(1 - 2n \cos(\theta/2) + n^2)^2}$$

$$= \pi a^2 n^2 \int_0^{2 \arccos(1/n)} \underbrace{\sin(\theta/2) d\theta}_{= 2 d(\cos(\theta/2))} \frac{(n \cos(\theta/2) - 1)(n - \cos(\theta/2))}{(1 - 2n \cos(\theta/2) + n^2)^2}$$

$\rightarrow$
 $\text{let } x = \cos(\theta/2)$
 $\theta = 0 \rightarrow x = 1$
 $\theta = 2 \arccos(1/n) \rightarrow x = 1/n$

$$= 2\pi a^2 n^2 \int_{1/n}^1 dx \frac{(nx - 1)(n - x)}{(1 - 2nx + n^2)^2}$$

$x = \cos(\theta/2)$
 $dx = -\frac{1}{2} \sin(\theta/2) d\theta$
 $y = nx$

$$\frac{d\theta}{dx} = \frac{2}{\sin(\theta/2)} = \frac{2}{\sqrt{1 - x^2}}$$

$$\sigma_T = 2\pi a^2 h^2 \int_{\frac{1}{h}}^1 dx \frac{(hx-1)(h-x)}{[(1+h^2) - 2hx]^2}$$

$$\begin{aligned} n-x &= n - \left(\frac{(1+h^2)-y}{2n} \right) \\ &= \frac{(n^2-1)+y}{2n} \end{aligned} \quad (9)$$

Let: $y = (1+h^2) - 2hx$ $x = \frac{(1+h^2)-y}{2n} \rightarrow (hx-1) = \frac{(1+h^2)-y}{2} - 1 = \frac{(n^2-1)-y}{2}$

$$dy = -2n dx \rightarrow dx = \frac{dy}{-2n}$$

$$x = \frac{1}{h} \rightarrow y = (1+h^2) - 2n\left(\frac{1}{h}\right) = 1+h^2-2 = n^2-1$$

$$x = 1 \rightarrow y = (1+h^2) - 2n = \cancel{(1+h^2)} (n-1)^2$$

$$\sigma_T = 2\pi a^2 h^2 \int_{(n-1)^2}^{n^2-1} \frac{dy}{2n} \frac{\left(\frac{(n^2-1)-y}{2}\right) \frac{(n^2-1)+y}{2n}}{y^2}$$

$$= 2\pi a^2 h^2 \frac{1}{8h^2} \int_{(n-1)^2}^{(n^2-1)} \frac{dy}{y^2} \frac{(n^2-1-y)(n^2-1+y)}{y^2}$$

$$= \frac{\pi}{4} a^2 \int_{(n-1)^2}^{n^2-1} du \frac{(n^2-1)^2 - y^2}{y^2} \quad \frac{a^2 - y^2}{y}$$

$$= \frac{\pi}{4} a^2 \int_{(n-1)^2}^{n^2-1} dy \left[\frac{(n^2-1)^2}{y^2} - 1 \right]$$

$$= \frac{\pi}{4} a^2 \left\{ (n^2-1)^2 \left(-\frac{1}{y} \right) \Big|_{(n-1)^2}^{n^2-1} - (n^2-1) + (n-1)^2 \right\}$$

$$= \frac{\pi}{4} a^2 \left\{ -(n^2-1)^2 \left(\frac{1}{n^2-1} - \frac{1}{(n-1)^2} \right) - (n^2-1) + (n-1)^2 \right\}$$

$$= \frac{\pi}{4} a^2 \left\{ -(n^2-1) + (n+1)^2 - (n^2-1) + (n-1)^2 \right\}$$

$$= \frac{\pi}{4} a^2 \left\{ \cancel{-n^2+1} + \cancel{n^2+2n+1} - \cancel{n^2+1} + \cancel{n^2-2n+1} \right\} = \boxed{\pi a^2}$$

(5.4)

Problem (a) Total cross-section for particle falling into center
 $U(r) = -\frac{A}{r^2} \quad (A > 0)$

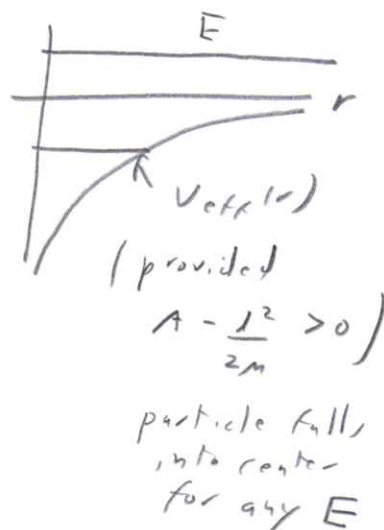
~~(a)~~

$$U_{\text{eff}}(r) = \frac{l^2}{2\mu r^2} + U(r)$$

$$= \frac{l^2}{2\mu r^2} - \frac{A}{r^2}$$

$$= -\frac{1}{r^2} \left(A - \frac{l^2}{2\mu} \right)$$

$$< 0 \quad \text{if} \quad A - \frac{l^2}{2\mu} > 0$$



Now, $l = \mu b v_\infty$

$$\text{So} \quad A - \frac{\mu^2 b^2 v_\infty^2}{2\mu} > 0$$

$$\text{or} \quad \frac{\mu b^2 v_\infty^2}{2} < A$$

$$b < \sqrt{\frac{2A}{\mu v_\infty^2}} = b_{\text{max}}$$

$$\sigma_T = \pi b^2$$

$$= \frac{\pi 2A}{\mu v_\infty^2}$$

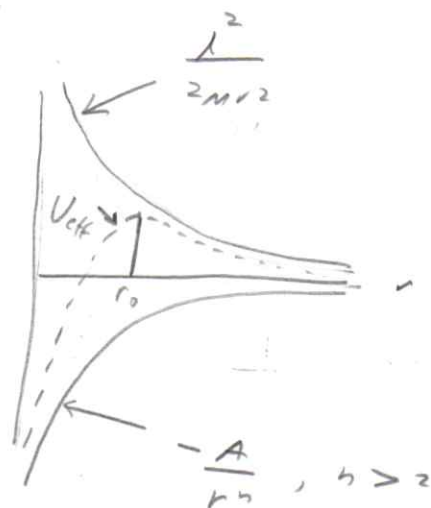
$$= \boxed{\frac{2\pi A}{\mu v_\infty^2}}$$

b) $V(r) = -\frac{A}{r^n}$, $A > 0$, $n > 2$

$$V_{\text{eff}}(r) = V(r) + \frac{l^2}{2mr^2}$$

$$= -\frac{A}{r^n} + \frac{l^2}{2mr^2}$$

~~Particle falls to infinity~~
for $E > V_{\text{eff}}|_{\text{max}}$



$$\frac{dV_{\text{eff}}}{dr} = +n\frac{A}{r^{n+1}} - \frac{l^2}{mr^3}$$

$$= \frac{nA}{r^{n+1}} - \frac{l^2}{mr^3}$$

$$\left. \frac{dV_{\text{eff}}}{dr} \right|_{r=r_0} = 0 \Leftrightarrow \left. \frac{nA}{r^{n+1}} \right|_{r=r_0} = \left. \frac{l^2}{mr^3} \right|_{r=r_0}$$

$$\left. \frac{nA}{r^{n-2}} \right|_{r=r_0} = \frac{l^2}{m}$$

$$\text{so } r_0 = \left(\frac{n\mu A}{l^2} \right)^{\frac{1}{n-2}}$$

~~$$\left. V_{\text{eff}} \right|_{\text{max}} = V_{\text{eff}}(r_0)$$~~

~~$$= -\frac{A}{\left(\frac{n\mu A}{l^2} \right)^{\frac{n-2}{n-2}}} + \frac{l^2}{2m \left(\frac{n\mu A}{l^2} \right)^{\frac{1}{n-2}}}$$~~

~~$$= -\frac{A \left(\frac{n\mu A}{l^2} \right)^{\frac{1}{n-2}}}{1} + \frac{l^2 \left(\frac{n\mu A}{l^2} \right)^{-\frac{1}{n-2}}}{2m}$$~~

~~$$= \frac{2m \left(\frac{n\mu A}{l^2} \right)^{\frac{1}{n-2}}}{1}$$~~

$$= \frac{2\mu A}{r_0^n} + \frac{l^2}{2\mu r_0^2} \left(\frac{n\mu A}{l^2} \right)^{-\frac{1}{n-2}}$$

$$= \frac{2\mu A}{r_0^n} + \frac{l^2}{2\mu r_0^2} \left(\frac{n\mu A}{l^2} \right)^{-\frac{1}{n-2}}$$

$$U_{eff} = U_{eff}(r_0)$$

$$= -\frac{A}{r_0^n} + \frac{l^2}{2\mu r_0^2}$$

$$= -\frac{2\mu A r_0^2 + l^2 r_0^n}{2\mu r_0^{n+2}}$$

$$= \frac{r_0^2 [-2\mu A + l^2 r_0^{n-2}]}{2\mu r_0^{n+2}}$$

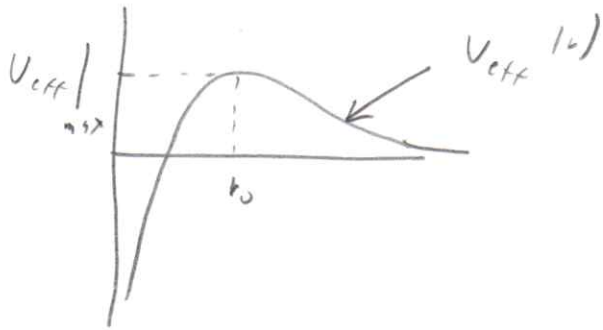
$$= \frac{1}{2\mu r_0^n} [-2\mu A + l^2 r_0^{n-2}]$$

$$= \frac{(n-2)A}{2\mu r_0^n}$$

$$= \frac{(n-2)A}{2} \frac{1}{\left(\frac{n\mu A}{l^2} \right)^{\frac{n}{n-2}}}$$

$$= \frac{(n-2)A}{2} \frac{1}{\left(\frac{n\mu A}{\mu^2 b^2 v_\infty^2} \right)^{\frac{n}{n-2}}}$$

$$= \frac{(n-2)A}{2} \left(\frac{\mu b^2 v_\infty^2}{An} \right)^{\frac{n}{n-2}}$$



Need $E > V_{eff}|_{max}$
for particle to fall to
center

Total cross section $\sigma_T = \pi b_{max}^2$

Where b_{max} given by setting $E = V_{eff}|_{max}$

$$\frac{1}{2} \mu v_{\infty}^2 = \frac{(n-2)A}{2} \left(\frac{\mu b_{max}^2 v_{\infty}^2}{An} \right)^{\frac{n}{n-2}}$$

$$\frac{\mu v_{\infty}^2}{A(n-2)} = \left(\frac{\mu b_{max}^2 v_{\infty}^2}{An} \right)^{\frac{n}{n-2}}$$

$$\left(\frac{\mu v_{\infty}^2}{A(n-2)} \right)^{\frac{n-2}{n}} = \frac{\mu b_{max}^2 v_{\infty}^2}{An}$$

$$\begin{aligned} \rightarrow b_{max}^2 &= \frac{An}{\mu v_{\infty}^2} \left(\frac{\mu v_{\infty}^2}{A(n-2)} \right)^{1-\frac{2}{n}} \\ &= n \left(\frac{\mu v_{\infty}^2}{A} \right)^{-\frac{2}{n}} \frac{1}{(n-2)^{\frac{n-2}{n}}} \\ &= n(n-2)^{\frac{2-n}{n}} \left(\frac{A}{\mu v_{\infty}^2} \right)^{\frac{2}{n}} \end{aligned}$$

$$\text{So } \sigma_T = \pi b_{max}^2 = \pi n(n-2)^{\frac{2-n}{n}} \left(\frac{A}{\mu v_{\infty}^2} \right)^{\frac{2}{n}}$$

particle motion in GR: (scattering calculation)

(1)

Problems 5.6, 5.7

$$ds^2 = -\left(1 - \frac{2GM}{rc^2}\right)^2 dt^2 + \left(1 - \frac{2GM}{rc^2}\right)^{-1} dr^2 + r^2 \left(d\theta^2 + \sin^2\theta d\phi^2 \right)$$

$\theta = \pi/2$

Now:

$$-c^2 = -c^2 \left(1 - \frac{2GM}{rc^2}\right) \left(\frac{dt}{d\lambda}\right)^2 + \left(1 - \frac{2GM}{rc^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + r^2 \left(\frac{d\phi}{d\lambda}\right)^2$$

where $\begin{cases} E = 1 & \text{for massive particle} \\ \lambda = \tau & \text{(proper time)} \end{cases}$

or $E = 0, \lambda = \text{affine parameter}$ for photon

~~Define~~
conserved quantities

$$E = \left(1 - \frac{2GM}{rc^2}\right) \left(\frac{dt}{d\lambda}\right) c^2$$

$$L = r^2 \frac{d\phi}{d\lambda}$$

E, L $\begin{cases} \text{energy, momentum of photon} \\ \text{energy, momentum for massive particle of mass } \mu \end{cases}$

So:

$$-c^2 = -c^2 \left(1 - \frac{2GM}{rc^2}\right) \frac{(\bar{E}^2/c^4)}{\left(1 - \frac{2GM}{rc^2}\right)^2} + \left(1 - \frac{2GM}{rc^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + r^2 \left(\frac{L}{r^2}\right)^2$$

$$-c^2 = -\left(1 - \frac{2GM}{rc^2}\right)^{-1} \frac{E^2}{c^2} + \left(1 - \frac{2GM}{rc^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + \frac{L^2}{r^2}$$

~~$$-c^2 = -\left(1 - \frac{2GM}{rc^2}\right)^{-1} \frac{E^2}{c^2} + \left(1 - \frac{2GM}{rc^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + \frac{L^2}{r^2}$$~~

$$-c^2 \left(1 - \frac{2GM}{rc^2}\right) = -\frac{E^2}{c^2} + \left(\frac{dr}{d\lambda}\right)^2 + \left(1 - \frac{2GM}{rc^2}\right) \frac{L^2}{r^2}$$

(2)

$$\frac{1}{2} \left(\frac{dr}{d\lambda} \right)^2 + \frac{1}{2} \left(1 - \frac{2GM}{rc^2} \right) \frac{L^2}{r^2} + \frac{1}{2} \epsilon c^2 \left(1 - \frac{2GM}{rc^2} \right) = \frac{1}{2} \frac{E^2}{c^2}$$

$$\boxed{\frac{1}{2} \left(\frac{dr}{d\lambda} \right)^2 + V_{\text{eff}}(r) = \frac{1}{2} \frac{E^2}{c^2}}$$

$$\text{where } V_{\text{eff}}(r) = \frac{1}{2} \left(1 - \frac{2GM}{rc^2} \right) \left(\frac{L^2}{r^2} + \epsilon c^2 \right)$$

$$= \left(1 - \frac{2GM}{rc^2} \right) \left(\frac{L^2}{2r^2} + \frac{\epsilon c^2}{2} \right)$$

$$= \frac{L^2}{2r^2} + \frac{\epsilon c^2}{2} - \frac{GM L^2}{c^2 r^3} - \frac{GM \epsilon}{r}$$

$$= \frac{1}{2} \left\{ \frac{L^2}{r^2} - \frac{2GM L^2}{c^2 r^3} + \epsilon c^2 - \frac{2GM \epsilon}{r} \right\}$$

$$= \frac{1}{2} \epsilon c^2 - \underbrace{\epsilon \frac{GM}{r} + \frac{L^2}{2r^2}}_{\text{Newtonian gravity for massive particle}} - \underbrace{\frac{GM L^2}{c^2 r^3}}_{\text{G-R correction}}$$

$$\frac{dr}{d\lambda} = \sqrt{2 \left(\frac{1}{2} \frac{E^2}{c^2} - V_{\text{eff}}(r) \right)}$$

Turning point: R when $\left. \frac{dr}{d\lambda} \right|_{r=R} = 0$

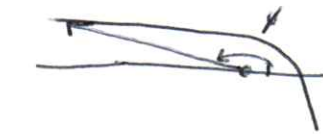
$$\frac{1}{2} \frac{E^2}{c^2} - V_{\text{eff}}(R) = 0$$

$$\frac{1}{2} \frac{E^2}{c^2} = V_{\text{eff}}(R)$$

$$= \frac{1}{2} \epsilon c^2 - \epsilon \frac{GM}{R} + \frac{L^2}{2R^2} - \frac{GM L^2}{c^2 R^3}$$

$$\frac{d\phi}{dr} = \frac{d\phi}{d\lambda} \frac{d\lambda}{dr}$$

$$= \frac{L}{r^2} \frac{1}{\sqrt{2 \left(\frac{1}{2} \frac{E^2}{c^2} - V_{\text{eff}}(r) \right)}}$$



(take - sign since ϕ ↓ as r goes from ∞ to $r_{\text{min}} \equiv R$)

$$= \frac{L}{r^2} \frac{1}{\sqrt{2 \left(\frac{1}{2} \cancel{E^2} - \epsilon \frac{GM}{R} + \frac{L^2}{2R^2} - \frac{GML^2}{c^2 R^3} - \frac{1}{2} \cancel{E^2} + \epsilon \frac{GM}{r} - \frac{L^2}{2r^2} + \frac{GML^2}{c^2 r^3} \right)}}$$

$$= \frac{L}{r^2} \frac{1}{\sqrt{2 \left(-\epsilon GM \left(\frac{1}{R} - \frac{1}{r} \right) + \frac{L^2}{2} \left(\frac{1}{R^2} - \frac{1}{r^2} \right) - \frac{GML^2}{c^2} \left(\frac{1}{R^3} - \frac{1}{r^3} \right) \right)}}$$

VERA

$$= \frac{L}{r^2} \frac{1}{\sqrt{2 \left(-\epsilon GM \left(\frac{1}{R} - \frac{1}{r} \right) + \frac{L^2}{2} \left(\frac{1}{R^2} - \frac{1}{r^2} \right) - \frac{GML^2}{c^2} \left(\frac{1}{R^3} - \frac{1}{r^3} \right) \right)}}$$

$$\Rightarrow \frac{L}{r^2} \frac{1}{\sqrt{2 \left(-\epsilon GM \left(\frac{1}{R} - \frac{1}{r} \right) + \frac{L^2}{2} \left(\frac{1}{R^2} - \frac{1}{r^2} \right) - \frac{GML^2}{c^2} \left(\frac{1}{R^3} - \frac{1}{r^3} \right) \right)}}$$

$$d\phi = \frac{L}{r^2} \frac{dr}{\sqrt{\dots}}$$

$$= \frac{L}{R} \frac{(-dy)}{\sqrt{\dots}}$$

$$u = \frac{R}{r}$$

$$dy = -\frac{R}{r^2} dr$$

$$\frac{1}{r} = \frac{u}{R}$$

$$d\phi = \frac{M - du}{\sqrt{\frac{2R^2}{L^2} \left(-\epsilon GM \left(\frac{1}{R} - \frac{1}{r} \right) + \frac{L^2}{2} \left(\frac{1}{R^2} - \frac{1}{r^2} \right) - \frac{GM L^2}{c^2} \left(\frac{1}{R^3} - \frac{1}{r^3} \right) \right)}}$$

$$= \frac{M - du}{\sqrt{\frac{2R^2}{L^2} \left(-\epsilon \frac{GM}{R} (1-u) + \frac{L^2}{2R^2} (1-u^2) - \frac{GM L^2}{c^2 R^3} (1-u^3) \right)}}$$

$$= \frac{M - du}{\sqrt{\cancel{M} (1-u^2) - \epsilon \frac{2GMR(1-u)}{L^2} - \frac{2GM}{Rc^2} (1-u^3)}}$$

$$= \frac{\cancel{M} du}{\sqrt{1-u^2} \sqrt{\cancel{M} \cancel{R} \cancel{R} \cancel{R} 1 - \epsilon \frac{2GMR(1-u)}{L^2} - \frac{2GM}{Rc^2} \frac{(1-u^3)}{(1-u^2)}}}$$

$$= \frac{- du / \sqrt{1-u^2}}{\sqrt{1 + A \left(\frac{1-u}{1-u^2} \right) + B \left(\frac{1-u^3}{1-u^2} \right)}}$$

so

$$\phi_m = \pi \int_0^1 \frac{du / \sqrt{1-u^2}}{\sqrt{1 + A \left(\frac{1-u}{1-u^2} \right) + B \left(\frac{1-u^3}{1-u^2} \right)}}$$

$$A = -\epsilon \frac{2GMR}{L^2}$$

$$B = -\frac{2GM}{Rc^2}$$

Approximation:

(5)

$$\frac{1}{\sqrt{1 + A\left(\frac{1-u}{1-u^2}\right) + B\left(\frac{1-u^3}{1-u^2}\right)}} \approx 1 - \frac{1}{2} A \left(\frac{1-u}{1-u^2} \right) - \frac{1}{2} B \left(\frac{1-u^3}{1-u^2} \right)$$

$$\phi_m = \frac{\pi}{2} \left\{ \underbrace{\int_0^1 \frac{du}{\sqrt{1-u^2}}}_{I_1} - \frac{1}{2} A \underbrace{\int_0^1 \frac{du}{\sqrt{1-u^2}} \left(\frac{1-u}{1-u^2} \right)}_{I_2} - \frac{1}{2} B \underbrace{\int_0^1 \frac{du}{\sqrt{1-u^2}} \left(\frac{1-u^3}{1-u^2} \right)}_{I_3} \right\}$$

$$I_1 = \int_0^1 \frac{du}{\sqrt{1-u^2}}$$

$$u = \cos \theta$$

$$du = -\sin \theta d\theta$$

$$u = 0, 1 \rightarrow \theta = \frac{\pi}{2}, 0$$

$$= - \int_{-\pi/2}^0 \frac{\sin \theta d\theta}{\sin \theta} = + \int_0^{\pi/2} d\theta = \boxed{\frac{\pi}{2}}$$

$$I_2 = \int_0^1 \frac{du}{\sqrt{1-u^2}} \underbrace{\left(\frac{1-u}{1-u^2} \right)}_{\frac{1}{1+u}} = \int_0^{\pi/2} d\theta \underbrace{\left(\frac{1}{1+\cos \theta} \right)}_{d\left(\tan\left(\frac{\theta}{2}\right) \right)} = \tan\left(\frac{\theta}{2}\right) \Big|_0^{\pi/2} = \boxed{1}$$

$$I_3 = \int_0^1 \frac{du}{\sqrt{1-u^2}} \left(\frac{1-u^3}{1-u^2} \right) = \int_0^1 \frac{du}{\sqrt{1-u^2}} \frac{(1-u)(1+u+u^2)}{(1-u)(1+u)}$$

$$= \int_0^1 \frac{du}{\sqrt{1-u^2}} \left[\frac{1}{1+u} + u \right]$$

$$\frac{1+u+u^2}{1+u} = \frac{1+u(1+u)}{1+u}$$

$$= \int_0^{\pi/2} d\theta \left[\frac{1}{1+\cos \theta} + \cos \theta \right]$$

$$= \frac{1}{1+u} + u$$

$$= 1 + \int_0^{\pi/2} \cos \theta d\theta$$

$$= 1 + \sin \theta \Big|_0^{\pi/2} = \boxed{2}$$

ϕ_m ,

6

$$\phi_m = \pi - \left[\frac{\pi}{2} - \frac{1}{2} A \cdot 1 - \frac{1}{2} B \cdot 2 \right]$$

$$= \frac{\pi}{2} + \frac{A}{2} + B$$

$$\theta = \pi - 2\phi_m$$

$$= \pi - 2 \left(\frac{\pi}{2} + \frac{A}{2} + B \right)$$

$$= -A - 2B$$

$$= -\epsilon \frac{2GMb}{L^2} + \frac{4GM}{Rc^2}$$

For small angle deflection $R \approx b$ (closest approach = impact parameter)

Then:

$$\theta = -\epsilon \frac{2GMb}{L^2} + \frac{4GM}{bc^2}$$

$$= \frac{2GM}{bc^2} \left(\frac{\epsilon b^2 c^2}{L^2} + 2 \right)$$

Light: $\epsilon = 0 \rightarrow \boxed{\theta = \frac{4GM}{bc^2}}$

Massive particle $\epsilon = 1 \rightarrow \theta = \frac{2GM}{bc^2} \left(\frac{b^2 c^2}{L^2} + 2 \right)$

$$L = \frac{L}{m} = \cancel{\frac{h}{m}} \frac{b}{m} \sqrt{\frac{E^2 - E_0^2}{c^2}} \quad (= b\gamma)$$

$$= \frac{b}{m} \sqrt{\frac{\gamma^2 m^2 c^4 - m^2 c^4}{c^2}}$$

$$= bc \sqrt{\gamma^2 - 1} = \boxed{\frac{bc\gamma}{\sqrt{1-\beta^2}}} = \frac{b\gamma_{\infty}}{\sqrt{1-\beta^2}}$$

$$\gamma = \frac{1}{\sqrt{1-\beta^2}} \rightarrow \gamma^2 = \frac{1}{1-\beta^2} \rightarrow \gamma^2 - 1 = \frac{1}{1-\beta^2} - 1 = \frac{\beta^2}{1-\beta^2}$$

Γ_{40} ,

$$\theta = \frac{2GM}{bc^2} \left(\frac{\frac{1}{c^2} (1-\beta^2)}{\frac{1}{c^2} \beta^2} + 2 \right)$$

$$= \frac{2GM}{bc^2} \left(\frac{1}{\beta^2} - 1 + 2 \right)$$

$$= \frac{2GM}{bc^2} \left(\frac{1}{\beta^2} + 1 \right)$$

$$= \boxed{\frac{2GM}{bc^2 \beta^2} (1 + \beta^2)}$$

Grodsky & Ryzhik:

6

p. 76
(2.264)
#8

$$\int \frac{x^3 dx}{\sqrt{R^3}} = \frac{c \Delta x^2 + b(4ac - 3b^2)x + a(8ac - 3b^2)}{c^2 \Delta \sqrt{R}} - \frac{3b}{2c^2} \int \frac{dx}{\sqrt{R}}$$

p. 94
(2.261)
#

$$\int \frac{dx}{\sqrt{R}} = -\frac{1}{\sqrt{-c}} \arcsin \left(\frac{2cx+b}{\sqrt{-\Delta}} \right)$$

$$c < 0, \Delta < 0$$

where $R = a + bx + cx^2$
 $\Delta = 4ac - b^2$
 $-\Delta = b^2 - 4ac$

suppose: $c = -1, b = 0, a = \frac{1}{b^2}$

$$\rightarrow \Delta = 4ac - b^2 = -\frac{4}{b^2}$$
$$\sqrt{-\Delta} = \frac{2}{b}$$

$$\int \frac{dy}{\left(\frac{1}{b^2} - y^2\right)^{\frac{1}{2}}} = -\frac{1}{\sqrt{+1}} \arcsin \left(\frac{-2y}{\left(\frac{2}{b}\right)} \right) = -\arcsin(-by) + \underline{\text{const}}$$

p. 96:
(2.264)
#5

$$\int \frac{dx}{\sqrt{R^3}} = \frac{2(2cx+b)}{\Delta \sqrt{R}}$$

- For Schwarzschild

$$d\tau^2 = - \left(1 - \frac{2M}{r} \right) dt^2 \quad (160)$$

for fixed (r, θ, ϕ) .

- Thus, the periods between emission and reception at $r = r_A$ and $r = r_B$ are related by

$$\frac{\Delta\tau_B}{\Delta\tau_A} = \left(\frac{1 - 2M/r_B}{1 - 2M/r_A} \right)^{1/2} \quad (161)$$

- The frequencies ($\omega_{A,B} := 2\pi/\Delta\tau_{A,B}$) are thus related by

$$\frac{\omega_B}{\omega_A} = \left(\frac{1 - 2M/r_A}{1 - 2M/r_B} \right)^{1/2} \quad (162)$$

- Hence, taking $r_B \rightarrow \infty$, $\omega_B = \omega_\infty$, $r_A = R$, $\omega_A = \omega$ yields

$$\omega_\infty = \omega \sqrt{1 - \frac{2M}{R}} \quad (163)$$

This is the gravitational redshift formula for Schwarzschild spacetime.

- The above expression reduces to the weak-field result in the limit of large R :

$$\omega_\infty \approx \omega \left(1 - \frac{M}{R} \right) \quad (164)$$

7.3 Particle motion in Newtonian gravity

- For a spherically symmetric source of attraction $V = -GMm/r$, total energy

$$E = \frac{1}{2}m|\vec{v}|^2 + V(r) \quad (165)$$

and angular momentum

$$\vec{L} = \vec{r} \times \vec{p} \quad (166)$$

are conserved.

- Using spherical symmetry to restrict to motion in the equatorial plane ($\theta = \pi/2$):

$$L = |\vec{r} \times \vec{p}| = mr^2 \frac{d\phi}{dt} \quad (167)$$

- In terms of L , the total total energy can be written as

$$E = \frac{1}{2}m \left(\frac{dr}{dt} \right)^2 + V_{\text{eff}}(r) \quad (168)$$

where the *effective potential* is given by

$$V_{\text{eff}}(r) := -\frac{GMm}{r} + \frac{1}{2} \frac{L^2}{mr^2} \quad (169)$$

- Exercise: Prove the above.
- The effective potential $V_{\text{eff}}(r)$ goes to zero (from below) as $r \rightarrow \infty$; it goes to ∞ at $r = 0$; and it has a minimum at $r = r_{\min} := L^2/GMm^2$. The minimum value of the effective potential is also the minimum allowed value of the energy given by $E_{\min} := -G^2M^2m^3/2L^2$.
- Exercise: Prove the above statements.
- There are three types of trajectories depending on the value of E :
 - (i) $E = E_{\min}$: A stable circular orbit at $r = r_{\min}$.
 - (ii) $E_{\min} < E < 0$: Bound orbits between turning points $r = r_1$ and $r = r_2$ ($r_1 < r_2$). These bound orbits are actually ellipses (discussed in more detail later).
 - (iii) $E \geq 0$: Scattering orbits that come in from $r = \infty$, make a closest approach at $r = r_1$, and then return to ∞ . ($E = 0$ is a parabola, $E > 0$ are hyperbolae.)

- Exercise: Show that for the circular orbit at $r = r_{\min}$, Kepler's 3rd law holds in the form

$$\Omega^2 = \frac{GM}{r_{\min}^3} \quad (170)$$

where $\Omega := d\phi/dt$ (which is constant for a circular orbit).

- To prove that the trajectories correspond to circles, ellipses, parabolas, etc., we need to find $\phi(r)$. Hence, we need to integrate

$$\frac{d\phi}{dr} = \frac{d\phi}{dt} \frac{dt}{dr} = \frac{L}{mr^2} \left[\frac{2}{m} (E - V_{\text{eff}}(r)) \right]^{-1/2} \quad (171)$$

- The integral is most simply done by making a change of variables to $u := 1/r$. Using (for $a < 0$)

$$\int \frac{du}{\sqrt{au^2 + bu + c}} = \frac{-1}{\sqrt{-a}} \sin^{-1} \left[\frac{2au + b}{\sqrt{b^2 - 4ac}} \right] \quad (172)$$

one can show that

$$\phi(r) = \phi_0 + \sin^{-1} \left[\frac{2au + b}{\sqrt{b^2 - 4ac}} \right] \quad (173)$$

where

$$a = \frac{-L^2}{m^2}, \quad b = 2GM, \quad c = \frac{2E}{m}, \quad u = \frac{1}{r} \quad (174)$$

- Exercise: Prove the above.
- Taking ϕ_0 to be the value of $\phi(r)$ at closest approach, one eventually finds

$$r(\phi) = \frac{\alpha}{1 + \epsilon \cos \phi} \quad (175)$$

where

$$\alpha = \frac{L^2}{GMm^2}, \quad \epsilon = \left(1 + \frac{2EL^2}{G^2M^2m^3} \right)^{1/2} \quad (176)$$

- Exercise: Prove the above.

- The equation

$$r(\phi) = \frac{\alpha}{1 + \epsilon \cos \phi} \quad (177)$$

corresponds to a *conic section*—i.e., a cut of a right circular cone by a plane with slope ϵ relative to horizontal. $\epsilon = 0$ corresponds to a circle; $0 < \epsilon < 1$ corresponds to ellipses; $\epsilon = 1$ corresponds to a parabola; and $\epsilon > 1$ corresponds to hyperbolae.

- For fixed L , the allowed values of ϵ are determined by the allowed values for E . In particular, $E = E_{\min}$ corresponds to $\epsilon = 0$; $E_{\min} < E < 0$ corresponds to $0 < \epsilon < 1$; $E = 0$ corresponds to $\epsilon = 1$; $E > 0$ corresponds to $\epsilon > 1$.
- For an ellipse, ϵ is the *eccentricity* and 2α is the *latus rectum*. (In terms of the semi-major axis a of an ellipse, a , α and ϵ are related by $\alpha = a(1 - \epsilon^2)$.)
- Exercise: Explicitly show that, for an ellipse with eccentricity ϵ and latus rectum 2α , the radial distance r from a point P on the ellipse to the focus satisfies Eq. (177), where ϕ is the angle between the line connecting the focal point to P and the semi-major axis.

7.4 Particle motion in Schwarzschild spacetime

- For Schwarzschild, the energy (at infinity) per unit particle rest mass

$$e := \frac{E}{m} = \left(1 - \frac{2M}{r}\right) \frac{dt}{d\tau} = -\frac{1}{m} g_{t\alpha} p^\alpha \quad (178)$$

and angular momentum per unit particle rest mass

$$\ell := \frac{L}{m} = r^2 \sin^2 \theta \frac{d\phi}{d\tau} = \frac{1}{m} g_{\phi\alpha} p^\alpha \quad (179)$$

are conserved.

- Since the Schwarzschild geometry is spherically symmetric, the trajectory will be in a 2-d plane. Taking this to be the equatorial plane ($\theta = \pi/2$),

$$\ell = r^2 \frac{d\phi}{d\tau} \quad (180)$$

- Exercise: Using the above conserved quantities, show that

$$-1 = \mathbf{u} \cdot \mathbf{u} = g_{\alpha\beta} u^\alpha u^\beta \quad (181)$$

is equivalent to

$$\mathcal{E} = \frac{1}{2} \left(\frac{dr}{d\tau} \right)^2 + V_{\text{eff}}(r) \quad (182)$$

where

$$\mathcal{E} := \frac{e^2 - 1}{2} \quad (183)$$

and

$$V_{\text{eff}}(r) := -\frac{M}{r} + \frac{\ell^2}{2r^2} - \frac{M\ell^2}{r^3} \quad (184)$$

- NOTE: The last term $-M\ell^2/r^3$ in the effective potential is what's responsible for the differences between Newtonian gravity and GR for particle motion in a spherically symmetric potential—e.g., the perihelion precession of Mercury, existence of plunge orbits, etc.
- The shape of the effective potential $V_{\text{eff}}(r)$ depends on the value of ℓ^2/M^2 .
- If $\ell^2/M^2 > 12$, the effective potential has two extrema corresponding to a local maximum and local minimum. The extreme values of r are given by

$$r = r_{\min}^{\max} := \frac{\ell^2}{2M} \left[1 \pm \sqrt{1 - \frac{12M^2}{\ell^2}} \right]. \quad (185)$$

- Exercise: Prove the above statements. (Hint: The local maximum and minimum are determined by setting $dV_{\text{eff}}(r)/dr = 0$.)
- If $\ell^2/M^2 = 12$, the effective potential has a point of inflection at $r_{\min} = r_{\max} = 6M =: r_{\text{ISCO}}$. This is the radius of the Innermost Stable Circular Orbit, hence the acronym ISCO.
- If $\ell^2/M^2 < 12$, the effective potential has no local maxima or minima.
- For $\ell^2/M^2 > 12$, there are five types of trajectories depending on the value of $\mathcal{E}$:
 - (i) $\mathcal{E} = \mathcal{E}_{\min}$: A stable circular orbit at $r = r_{\min}$.
 - (ii) $\mathcal{E}_{\min} < \mathcal{E} < 0$: Bound orbits between turning points $r = r_1$ and $r = r_2$ ($r_1 < r_2$). Unlike the case for Newtonian gravity, these bound orbits are not closed; they are ellipses whose turning points precess (more about this later).
 - (iii) $0 \leq \mathcal{E} < \mathcal{E}_{\max}$: Scattering orbits that come in from $r = \infty$, make a closest approach at $r = r_1$, and then return to ∞ . (The particle can actually orbit around the centre of curvature a number of times before returning to ∞ .)
 - (iv) $\mathcal{E} = \mathcal{E}_{\max}$: An unstable circular orbit at $r = r_{\max}$. Unstable circular orbits do not exist for Newtonian gravity.
 - (v) $\mathcal{E} > \mathcal{E}_{\max}$: A plunge orbit in which the particle comes in from $r = \infty$ and eventually hits the surface of the star or falls inside the event horizon ($r = 2M$) of a black hole. These plunge orbits do not exist for Newtonian gravity.

- Exercise: Show that for the stable circular orbit at $r = r_{\min}$, Kepler's 3rd law holds in the form

$$\Omega^2 = \frac{M}{r_{\min}^3} \quad (186)$$

where $\Omega := d\phi/dt$ (note the derivative with respect to t not τ).

- Bound orbits precess. If we define

$$\delta\phi_{\text{prec}} := \Delta\phi - 2\pi \quad (187)$$

where $\Delta\phi$ is calculated from one turning point $r = r_1$ back to $r = r_1$, one can show that the first-order correction to the Newtonian result ($\delta\phi_{\text{prec}} = 0$) is

$$\delta\phi_{\text{prec}} \approx \frac{6\pi G}{c^2} \frac{M}{a(1 - \epsilon^2)} \quad (188)$$

- The largest precession occurs for small a and large ϵ —i.e., Mercury in our solar system. Substituting the values for Mercury gives $\delta\phi_{\text{prec}} \approx 43$ arcseconds per century, in agreement with observation. This retrodiction was one of the major triumphs of GR.

- Radial infall from rest at $r = \infty$ has $\mathcal{E} = 0$, $\ell = 0$, $\theta = \text{const}$, and $\phi = \text{const}$. The effective potential simplifies to $V_{\text{eff}}(r) = -M/r$ and the radial equation can be written as

$$\frac{d\tau}{dr} = -\sqrt{\frac{r}{2M}} \quad (189)$$

It has solution

$$\tau - \tau_* = -\frac{2}{3} \frac{1}{\sqrt{2M}} r^{3/2} \quad (190)$$

where $\tau = \tau_*$ corresponds to $r = 0$.

- Note that it takes a *finite* amount of proper time to fall from any finite r (e.g., $r = 10M$) to $r = 2M$.
- The same radial infall, described in terms of the Schwarzschild coordinate time t , satisfies the differential equation

$$\frac{dt}{dr} = \frac{dt}{d\tau} \frac{d\tau}{dr} = -\sqrt{\frac{r}{2M}} \left(1 - \frac{2M}{r}\right)^{-1} \quad (191)$$

- This has solution

$$t - t_* = 2M \left[-\frac{2}{3} \left(\frac{r}{2M}\right)^{3/2} - 2 \left(\frac{r}{2M}\right)^{1/2} + \log \left| \frac{\sqrt{r/2M} + 1}{\sqrt{r/2M} - 1} \right| \right] \quad (192)$$

where $t = t_*$ corresponds to $r = 0$.

- Exercise: Prove the above.
- Note that, contrary to what we found for proper time, it takes an *infinite* amount of coordinate time to fall from any finite r (e.g., $r = 10M$) to $r = 2M$.

7.5 Light rays in Schwarzschild spacetime

- For light rays in Schwarzschild spacetime, the energy (at infinity)

$$e := \left(1 - \frac{2M}{r}\right) \frac{dt}{d\lambda} = -g_{t\alpha} p^\alpha \quad (193)$$

and angular momentum

$$\ell := r^2 \sin^2 \theta \frac{d\phi}{d\lambda} = g_{\phi\alpha} p^\alpha \quad (194)$$

are conserved, where $p^\alpha := dx^\alpha/d\lambda$ with λ an affine parameter for the motion.

- Spherical symmetry implies motion in a 2-d plane. Taking this to be the equatorial plane ($\theta = \pi/2$),

$$\ell = r^2 \frac{d\phi}{d\lambda} \quad (195)$$

- Exercise: Using the above conserved quantities, show that

$$0 = \mathbf{u} \cdot \mathbf{u} = g_{\alpha\beta} u^\alpha u^\beta \quad (196)$$

implies

$$\frac{1}{b^2} = \frac{1}{\ell^2} \left(\frac{dr}{d\lambda} \right)^2 + W_{\text{eff}}(r) \quad (197)$$

where

$$b^2 := \frac{\ell^2}{e^2} \quad (198)$$

and

$$W_{\text{eff}}(r) := \frac{1}{r^2} \left(1 - \frac{2M}{r} \right) \quad (199)$$

- NOTE: The motion depends only on the ratio ℓ/e , since a different choice of affine parameter changes the values of ℓ and e , but not their ratio.
- b has the interpretation of an *impact parameter*—it is the perpendicular distance (at large r) between the direction of the light ray and a parallel line passing through the centre of curvature. In other words, $\ell = bp$ at large r , where p is the magnitude of the linear momentum.
- The shape of the effective potential $W_{\text{eff}}(r)$ is independent of ℓ .
- The effective potential has one extremum corresponding to a local maximum at $r = r_{\text{max}} = 3M$. The value of $W_{\text{eff}}(r)$ at $r = 3M$ is

$$W_{\text{max}} := W_{\text{eff}}(r = 3M) = \frac{1}{27M^2} \quad (200)$$

$W_{\text{eff}}(r)$ goes to zero (from above) as $r \rightarrow \infty$; it equals 0 at $r = 2M$.

- Exercise: Prove the above.
- There are three types of trajectories depending on the value of $1/b^2$:
 - (i) $0 < 1/b^2 < W_{\text{max}}$: Scattering orbits that come in from $r = \infty$, make a closest approach at $r = r_1$, and then return to ∞ . (The light ray can actually orbit around the centre of curvature a number of times before returning to ∞ .) Hence light is deflected by a spherically symmetric potential in GR.
 - (ii) $1/b^2 = W_{\text{max}}$: A unstable circular orbit at $r = r_{\text{max}} = 3M$.
 - (iii) $1/b^2 > W_{\text{max}}$: A plunge orbit in which light comes in from $r = \infty$ and eventually hits the surface of the star or falls inside the event horizon ($r = 2M$) of a black hole.

Note that a small impact parameter b means small angular momentum ℓ , and hence a greater chance for capture by the star or black hole.
- To determine the deflection of light, one needs to integrate

$$\frac{d\phi}{dr} = \frac{d\phi}{d\lambda} \frac{d\lambda}{dr} = \pm \frac{1}{r^2} \left[\frac{1}{b^2} - W_{\text{eff}}(r) \right]^{-1/2} \quad (201)$$

- We define the deflection angle via

$$\delta\phi_{\text{def}} := \Delta\phi - \pi \quad (202)$$

where

$$\Delta\phi := 2 \int_{\infty}^{r_1} \frac{d\phi}{dr} dr \quad (203)$$

with r_1 being the closest approach of the trajectory.

- Keeping only the leading order correction terms to the Newtonian result, we find

$$\delta\phi_{\text{def}} \approx \frac{4GM}{bc^2} \quad (204)$$

- Exercise: Prove the above.
- For light grazing the Sun (i.e., $M = M_{\odot}$, $b = R_{\odot}$), $\delta\phi_{\text{def}} \approx 1.7$ arcseconds, which was verified by Eddington in 1919 during a solar eclipse. This prediction was another major success of GR.
- The deflection of light as it passes a source of curvature also gives rise to a *time delay* effect, as compared to straight line travel time in Newtonian gravity.
- To calculate the excess time delay one needs to integrate

$$\frac{dt}{dr} = \frac{dt}{d\lambda} \frac{d\lambda}{dr} = \pm \frac{1}{b} \left(1 - \frac{2M}{r}\right)^{-1} \left[\frac{1}{b^2} - W_{\text{eff}}(r)\right]^{-1/2} \quad (205)$$

- Consider sending light or a radar signal from the Earth (past the Sun) to a reflector located at r_R , and then waiting for the reflected signal. The total travel time of the signal is given by

$$(\Delta t)_{\text{tot}} = 2t(r_{\oplus}, r_1) + 2t(r_R, r_1) \quad (206)$$

where r_1 is the closest approach to the Sun, $r_{\oplus}$ and r_R are distances of the Earth and reflector from the Sun, and $t(r, r_1)$ is the time that it takes the signal to travel from r to r_1 .

- We define the excess time delay as

$$(\Delta t)_{\text{excess}} := (\Delta t)_{\text{tot}} - 2\sqrt{r_{\oplus}^2 - r_1^2} - 2\sqrt{r_R^2 - r_1^2} \quad (207)$$

where the last two terms give the travel time from Newtonian theory.

- If we assume $r_1 \ll r_{\oplus}$ and r_R , and carry out the calculation keeping only the first-order correction terms, we find

$$(\Delta t)_{\text{excess}} \approx \frac{4GM}{c^3} \left[\log \left(\frac{4r_R r_{\oplus}}{r_1^2} \right) + 1 \right] \quad (208)$$

- Exercise: Prove the above.
- The excess time delay has also been confirmed experimentally.